



# Unsupervised Multi-Task Domain Adaptation

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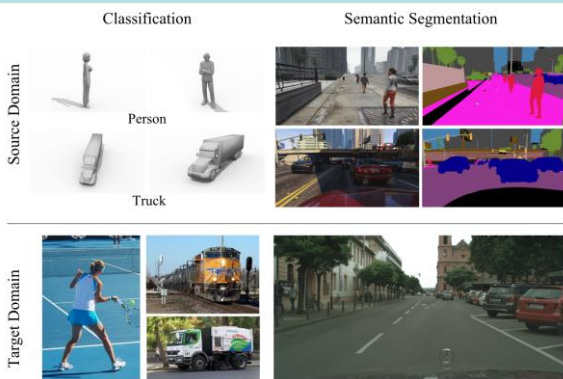
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**Unsupervised domain adaptation** aims to generalize a model's capability applied on the target domain (without labels) with the model trained using labeled data from the source domain.

**Multi-task learning** aims to learn multiple tasks jointly by exploiting their relatedness to improve the generalization performance for each task.

**Does MTL further improve the generalization ability of a model for domain adaptation?**

## MTL-DA SETTING

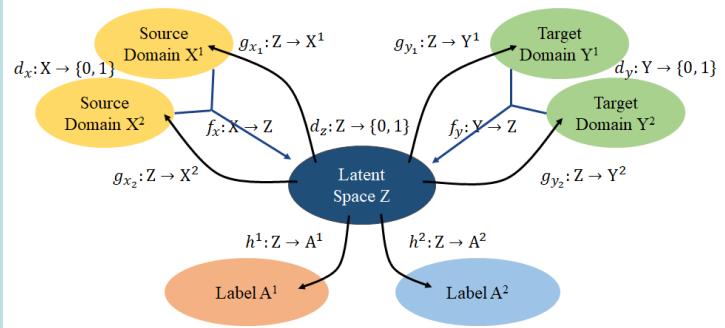


### VidDA2017 dataset

- The dataset contains samples and ground truth labels for more than one task.
- Each task contains samples of the source and the target domains.

X. Peng, B. Usman, N. Kaushik, J. Hoffman, D. Wang and K. Saenko, "VisDA: The Visual Domain Adaptation Challenge," 2017.

## APPROACH



### Developed upon the I2I Adapt framework

- Not designed for a specific task; should accommodate more tasks such as object detection.
- Allow the customization of the model's complexity to meet specific needs.
- Simultaneously adapt multiple tasks using a single adaptation architecture.

Z. Murez, S. Kolouri, D. Kriegman, R. Ramamoorthi, and K. Kim, "Image to Image Translation for Domain Adaptation," IEEE CVPR, 2018.

## RESULTS

### Image Classification

Setup	Source only	MTL	Single-task adaptation	Multi-task adaptation
aeroplane	70.39	65.32	69.71	<b>71.21</b>
bicycle	26.91	26.91	<b>80.79</b>	69.71
bus	52.51	43.07	65.03	<b>75.75</b>
car	<b>69.40</b>	60.43	65.72	66.47
horse	77.67	75.64	83.26	<b>87.10</b>
knife	4.22	5.18	28.19	<b>39.88</b>
motorcycle	82.06	<b>84.69</b>	74.99	81.16
person	38.31	46.69	55.19	<b>64.56</b>
plant	77.25	71.10	79.34	<b>82.25</b>
skateboard	21.60	<b>26.10</b>	25.77	22.59
train	83.24	<b>86.37</b>	78.47	75.52
truck	9.10	13.83	<b>16.53</b>	15.45
accuracy	51.05	50.44	60.25	<b>62.64</b>

- Source only method performs the worst, MTL does not reduce domain shift. Domain adaptation can help.
- Unsupervised multi-task domain adaptation can further enhance the ability of domain adaptation.

### Semantic Segmentation

Setup	Source only	MTL	Single-task adaptation	Multi-task adaptation
road	23.42	20.06	71.26	<b>79.17</b>
sidewalk	22.32	20.68	27.76	<b>34.69</b>
building	40.54	53.89	70.82	<b>78.40</b>
wall	2.88	5.39	9.75	<b>20.30</b>
fence	4.99	8.55	11.07	<b>14.08</b>
pole	10.50	19.36	19.29	<b>30.69</b>
traffic light	12.79	16.14	8.01	<b>20.21</b>
traffic sign	0.26	0.16	0.34	<b>1.14</b>
vegetation	73.40	<b>77.95</b>	77.09	75.95
terrain	<b>26.91</b>	21.62	24.23	19.91
sky	35.01	72.04	67.13	<b>76.45</b>
person	43.88	30.94	37.91	<b>52.95</b>
rider	<b>0.08</b>	0.07	0.02	0.07
car	68.44	31.59	65.84	<b>75.26</b>
truck	9.83	5.41	7.35	<b>13.99</b>
bus	3.86	6.51	9.10	<b>17.64</b>
train	0.00	0.06	0.15	<b>0.53</b>
motorcycle	0.18	0.41	0.07	<b>1.14</b>
bicycle	0.00	0.00	0.00	0.00
mIoU	19.96	20.57	26.69	<b>32.24</b>