

# Small Object Detection by Generative and Discriminative Learning

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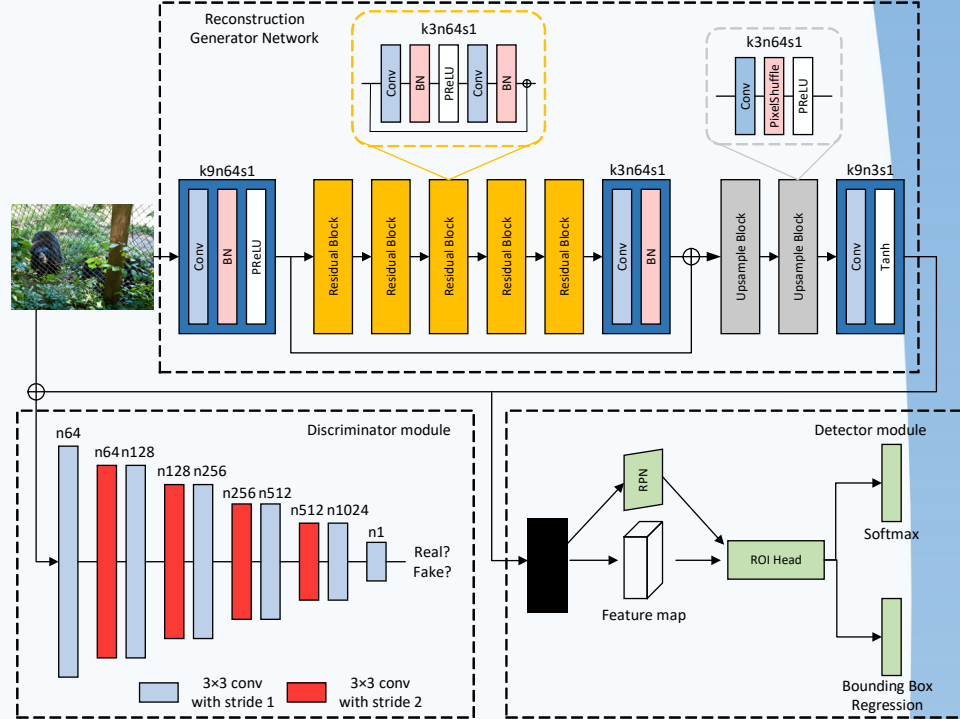
## Problem

Small object detection is a challenging problem due to the limited information. Existing methods focus on improving classification accuracy but still suffer from the limitation of bounding box prediction.

## Solution

We argue a preferable way to implement a reconstruction network on the detection module, which is different from the previous work that applies reconstruction to the discriminator module. The purpose of such a framework design is to deblur objects and produce more details for bounding box prediction so that the detection module can identify the anchor box of small object more precisely.

## Result



## Framework

We propose a detection framework By generative and discriminative learning.

A reconstruction generator network is designed to reconstruct the mapping from low frequency to high frequency for anchor box prediction.

A detector module extracts the regions of interest (ROIs) from generated results and implements a RoI-Head to predict object category and refine bounding box.

- $$L_{adv} = \frac{1}{m} \sum_{i=1}^m \log(1 - D_{\theta_D}(G_{\theta_G}(z_{LR}^{(i)})))$$
- $$L_{MSE} = \frac{1}{m} \sum_{i=1}^m \|z_{HR}^{(i)} - G_{\theta_G}(z_{LR}^{(i)})\|_2^2$$
- $$L_{TV} = \frac{1}{r^2 WH} \sum_{i=1}^r \sum_{j=1}^H \|\nabla G_{\theta_G}(z_{LR}^{(i,j)})\|$$
- $$L_{cls} = \frac{1}{m} \sum_{i=1}^m [-\left(\log(p^{(i)} p^{*(i)} + (1 - p^{(i)})(1 - p^{*(i)})) - \log(D_{cls}(G_{\theta_G}(z_{LR}^{(i)}))) + \log(D_{cls}(z_{HR}^{(i)}))\right)]$$
- $$L_{reg} = \frac{1}{m} \sum_{i=1}^m \sum_{j \in (x,y,w,h)} [u_i \geq 1] (S_{L_1}(t_{SR}^{i,j} - t^{*(i,j)}))$$
- $$\max_{\theta_D} \min_{\theta_G} (\frac{1}{m} \sum_{i=1}^m \log D_{\theta_D}(z_{HR}^{(i)}) + \alpha L_{adv} + \beta L_{cls} + \gamma L_{reg} + L_{TV} + L_{MSE})$$