

# Enhanced Feature Pyramid Network for Semantic Segmentation



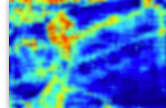
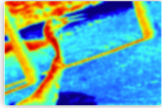
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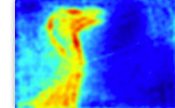
## Observation

### 1. Semantic gap between shallow and deep features

- Shallow feature layers contain low-level appearance information (e.g., edges, lines, and corners)
- Deep layers contain more semantic information to distinguish different classes



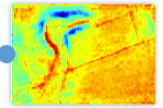
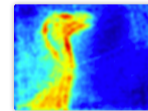
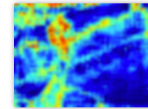
shallow layer



deep layer

### 2. In the encoder-decoder architecture, a skip connection is frequently used to aggregate multi-scale context information

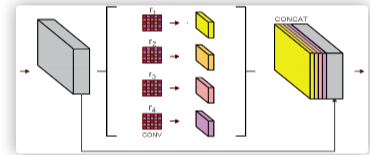
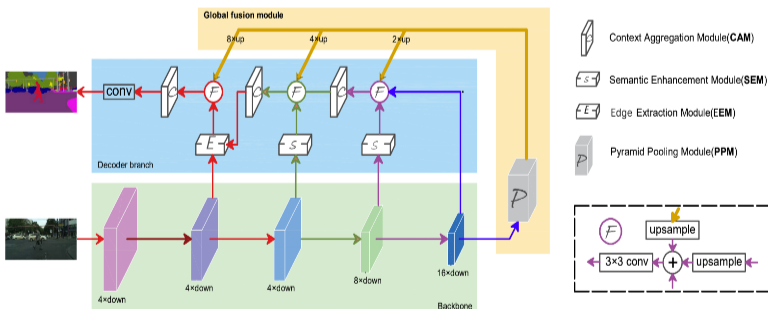
- The semantic difference between the shallow features and the deep features hinders the effective fusion of the different features
- Simply combining the shallow feature with the deep feature will bring some background "noise", which will affect the robustness of the feature



## Networks

- Enhanced Feature Pyramid Network (EFPN)** : To bridge the semantic gap and realize the effective fusion of multi-layer features

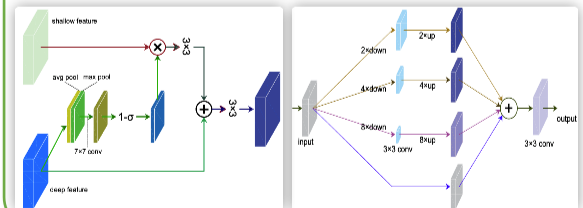
- Global fusion model (GFM)** : Remedy the drawback of U-shape networks that top-down signals are gradually diluted



- Semantic Enhancement Module (SEM)** : Enhance the shallow features

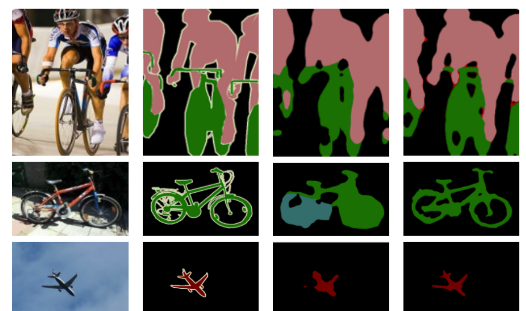
- Edge Extraction Module (EEM)** : Based on attention

- Context Aggregation Module (CAM)** : Better aggregation



## Experiment & Conclusion

- First, it is verified that the direct use of jump connections to fuse shallow features and deep features will affect the robustness of features
- Second, the effectiveness of global fusion module in encoder branch is further evaluated
- Finally, we prove the effectiveness of EFPN in bridging the semantic gap through experiments



(a) Images (b) Ground Truth (c) Baseline (d) Ours