

Motivation

movements

Contributions

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Challenges

Channel-Wise Dense Connection Graph Convolutional Network For Skeleton-Based Action Recognition

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1.Introduction

Construct global information for action and select more related features

Generate and utilize features to adapt for difference on action

Extract the motion features from skeleton data and concatenating them

Introduce a channel-wise attention module to emphasize channels with

Use dense connection to ensure reuse of skeleton features and to

Our model shows competitive performance with the state-of-the-art

2. Background

Joints as vertices (V) and the connection between joints as edges (E)

coordinate of corresponding joint and its estimation confidence

 $A_{i,i} = 1$ if *i*-th joint and *j*-th joint is connected, and 0 otherwise

Joints are connected in one frame and adjacent frame

Spatial temporal graph convolutional networks (ST-GCN)

weight distribution of convolution on spatial dimension

which are not existed in the original graph

Convolution operation on spatial and temporal dimension

A mapping strategy to determine the size of convolution kernel and

Two-stream adaptive graph convolutional networks (2s-AGCN)

Temporal dimension convolution is similar to classical image convolution

Introduced an adjacency matrix, the elements of it are parameterized

Introduced a similarity matrix, whose elements denotes the similarity of

Generate the connections and their importance between two vertices,

and optimized together in the training process and can be arbitrary

Each vertices contains three channels of information, a two-dimensional

Build an skeleton-based action recognition system

The importance of different channels varies in actions

Some human actions only involve a small part of bodies

Extracted temporal feature representation

generate a larger and sufficient features map

model on two large datasets, NTU-RGB+D and Kinetics

Given M frames and N joints of skeleton sequence

Confusion on reversing actions

with original spatial features

important features

Skeleton Graph

Skeleton graph G = (V,E)

Adjacency matrix A

Baseline Model

Based on ST-GCCN

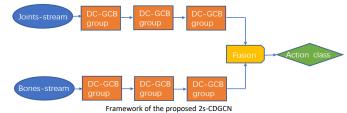
values

two vertices

3. Two-stream Channel-wise Dense Connection GCN(2s-CDGCN)

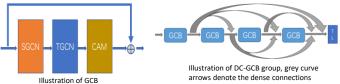
Data Preprocessing

- Vertice's joint coordinate $v_i = (x_i, y_i)$
- Bone information, extracted from neighboring vertices, $b_{ii} = (x_i x_i, y_i y_i)$
- Motion information of joints and bones, extracted from consecutive frames of data, $m_i = (x_i^{t+1} - x_i^t, y_i^{t+1} - y_i^t)$
- Concatenate the information of joints and their motion in the frame dimension. The same procedure was conducted with the bones.



Model Structure

- Two-stream fashion, each stream consists of 12 graph convolution blocks with late fusion
- A graph convolution block (GCB), consists of a spatial GCN, a temporal GCN and a channel-wise attention module (CAM), followed by a residual connection
 - A DC-GCB group, consists of 4 GCBs with Dense connection implemented, followed by a transition laver



- Channel-wise attention module (CAM)
- Encode the entire spatial and temporal feature on a channel as a global feature descriptor
- Analyze the interdependence between channels, generate a set of attention weights of
- corresponding channels
- A channel-wise multiplication is made to represent a global information based on feature channels.
- Concatenation of all the preceding graph convolution block's output features maps

- ٠ Training batch size 64 and Test batch size 64
- Stochastic gradient descent (SGD) as optimizer with an initial learning rate 0.1 and a cosine learning rate decay
- The weight decay of 0.0001 and Nesterov momentum of 0.9 are set
- The hyperparameter reduction ratio r, used in channel-wise attention module, is set to 16

4.Experiments and Results

Dataset

NTU-RGB+D

- 60 different action classes including daily and health-related actions
- 25 body joints collected by Microsoft Kinect v2
- 40 distinct subjects recorded from 3 different horizontal angles
- Cross-subject evaluation and cross-view evaluation
- Kinetics
- 400 action classes with at least 400 video clips
- 18 body joints obtained by OpenPose toolbox

Methods	Cross Subject (%)	Cross View (%)	
2s-AGCN [4]	88.5	95.1	
2s-CDGCN without DC	89.3	95.9	
2s-CDGCN without CAM	89.5	95.5	
2s-CDGCN	90.0	96.1	

- Example of activations in CAM
- Choose dataset NTU-RGB+D to test the Top-1 accuracy
- Valid effect on improving the performance of the model
- The module learns the non-linear relations between channels and the scale is not one-hot encoding
- Emphasize multiple channels with more importance
- Dense Connection
 - Performance improvement shows that the network takes the advantage of Dense Connection
- Produces a larger and sufficient features map to achieve better results
- CAM, compared with DC, achieves higher accuracy improvements on cross-view benchmark, and vice versa, which can be explained by the relationship between modification modules and NTU-RGB+D setup
- Comparison with the State-of-the-Art methods
- Methods include hand-crafted methods [42][49], CNN-based methods [5][44][43][47], RNN-based methods [9][10][45][11] and GCN-based methods[1][14][13][15][48][46][4]

Methods	Top-1(%)	Top-5(%)	Methods	Cross-Subject(%)	Cross-View(%)	
Feature [49]	14.9	25.8	Lie Group [42]	50.1	52.8	
	,		Deep LSTM [20]	60.7	67.3	
Deep LSTM [20]	16.4	35.3	STA-LSTM [11]	73.4	81.2	
TCN [43]	20.3	40.0	TCN [43]	74.3	83.1	
ST-GCN [3]	30.7	52.8	C-CNN + MTLN [44]	79.6	84.8	
			VA-LSTM [45]	79.4	87.6	
AS-GCN [1]	34.8	56.5	ST-GCN [3]	81.5	88.3	
2s-AGCN [4]	36.1	58.7	SR-TSL [46]	84.8	92.4	
DGNN [48]	36.9	59.6	HCN [5]	86.5	91.1	
	0.015		3scale ResNet152 [47]	85.0	92.3	
GCN-NAS [14]	37.1	60.1	RA-GCN [15]	85.9	93.5	
28-CDGCN	37.0	59.8	DenseIndRNN [10]	86.7	93.7	
Comparison on Kinetics dataset			PB-GCN [13]	87.5	93.2	
			AS-GCN [1]	86.8	94.2	
			AGC-LSTM [9]	89.2	95.0	
 Outperforms hand-crafted 			2s-AGCN [4]	88.5	95.1	
			GCN-NAS [14]	89.4	95.7	
methods, CNN and RNN		DGNN [48]	89.9	96.1		
		2s-CDGCN	90.0	96.1		
methods w	ith a large	margin	Comparison on NTU-RGB+D dataset			

A competitive result comparing with the state-of-the-art GCN-based methods



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 - Transition layer between blocks to reduce the number of features

Training

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