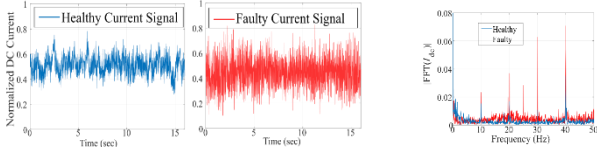


Russell Sabir^{1,2}, Daniele Rosato¹, Sven Hartmann¹ and Clemens Gühmann²

¹SEG Automotive Germany GmbH, ²Chair of Electronic Measurement and Diagnostic Technology & Technische Universität Berlin

1. Introduction and Motivation

Synchronous Machines Faults



1-D convolution neural network with Wavelet Packet Transform

98.8% accuracy

(I. Kao, W. Wang, Y. Lai and J. Peng, "Analysis of Permanent Magnet Synchronous Motor Fault Diagnosis Based on Learning," in IEEE Transactions on Instrumentation and Measurement)

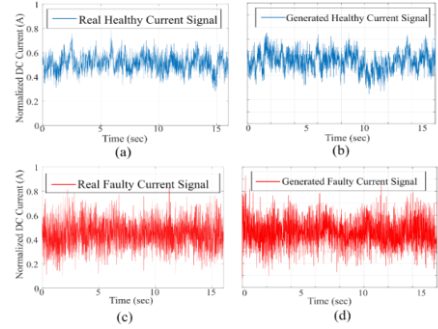
Stacked Autoencoder with softmax layer **96.4% accuracy**

(I. Kao, W. Wang, I. Chiang and J. Peng, "Implementation of Permanent Magnet Synchronous Motor Fault Diagnosis by a Stacked Autoencoder," 2018 IEEE International Conference on Consumer Electronics-Taiwan (ICCE-TW))

Challenges with Deep Learning Algorithms

- Deep Learning methods require large amounts of data
- Algorithms don't generalize with large data

5. Generated Results



Normalized (between 0 and 1) E-Drive DC (a) Real current signal of Healthy Machine (b) Generated current signal of healthy machine (c) Real current signal of faulty machine (d) Generated current signal of faulty machine

2. Fréchet Inception Distance (FID)

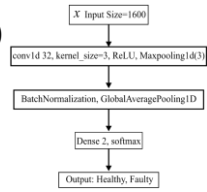
$$FID = \|\mu_1 - \mu_2\|^2 + Tr(C_1 + C_2 - 2(C_1 C_2)^{1/2})$$

where, μ_1 and μ_2 are the feature wise mean

C_1 and C_2 are the covariance matrices

And Tr is the trace of the matrix

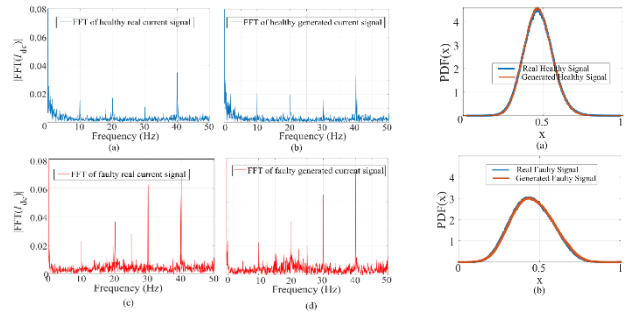
FID Threshold: 5 x 1E-5



3. Training Parameters

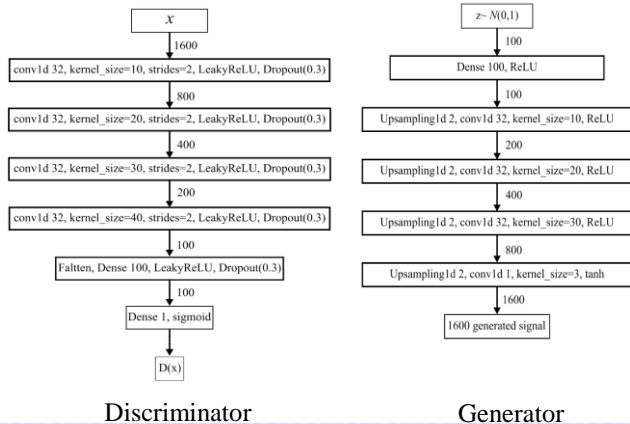
- Training Data: 1400 Healthy and 1400 Faulty Current Signals
- Sampling Frequency: 100 Hz
- Learning rate of 0.0002 and beta of 0.5
- Discriminator Loss Function: binary cross-entropy
- Generator Loss Function: sparse categorical cross-entropy
- Adam Optimizer

6. Evaluation of results



- Creativity:** The generated signals are not duplicates of the real signals.
- Diversity:** The generated signals are not duplicates of each other.

4. 1d DCGAN Architecture



$$SSIM(x, y) = \frac{(2\mu_x\mu_y + c_1)(2\sigma_{xy} + c_2)}{(\mu_x^2 + \mu_y^2 + c_1)(\sigma_x^2 + \sigma_y^2 + c_2)}$$

μ_x is the mean value of x

μ_y is the mean value of y

σ_x^2 is the variance of x

σ_y^2 is the variance of y

σ_{xy} is the covariance of x and y

$c_1 = (k_1 L)^2$ and $c_2 = (k_2 L)^2$ are the variables to stabilize the division with weak denominator

In our case $k_1 = k_2 = 0.05$, and L is the dynamic range of the signal value

$$Diversity = - \sum_{i=1}^m p_i \log p_i$$

where, $p_i = \frac{|C_i|}{\sum_{i=1}^m |C_i|}$

m is the number of clusters

$|C_i|$ is the number of signals in the cluster

where $i = 1, \dots, m$

$$Creativity = \frac{\text{Number of Nonduplicate Signal}}{\text{Number of Signals in the generated dataset}}$$

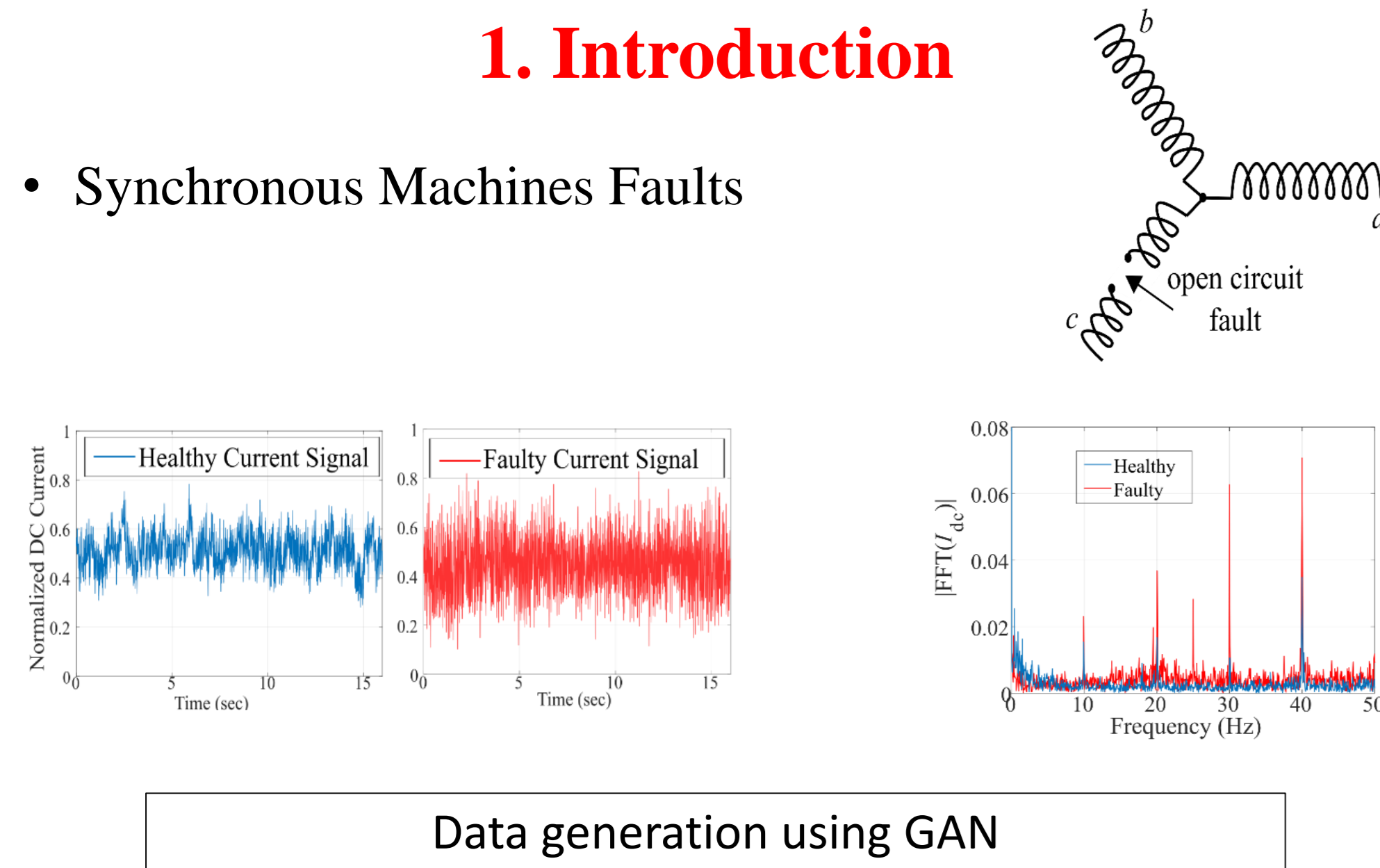
	1d DCGAN trained on Healthy signals	1d DCGAN trained on Faulty signals	Optimal values for 10000 signal dataset
Creativity	1	1	1
Diversity	9.0	8.7	9.2

7. Conclusion

- 1d signals generation using DCGAN
- Evaluation using FID distance
- Further evaluation using Creativity and Diversity
- Generated Signals are statically rich and are uncorrelated to the real signals

1. Introduction

- Synchronous Machines Faults



2. Motivation

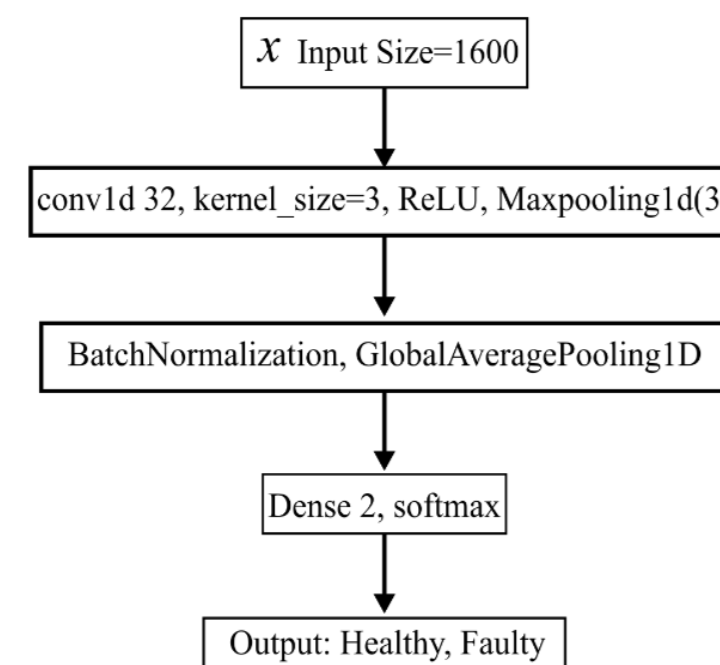
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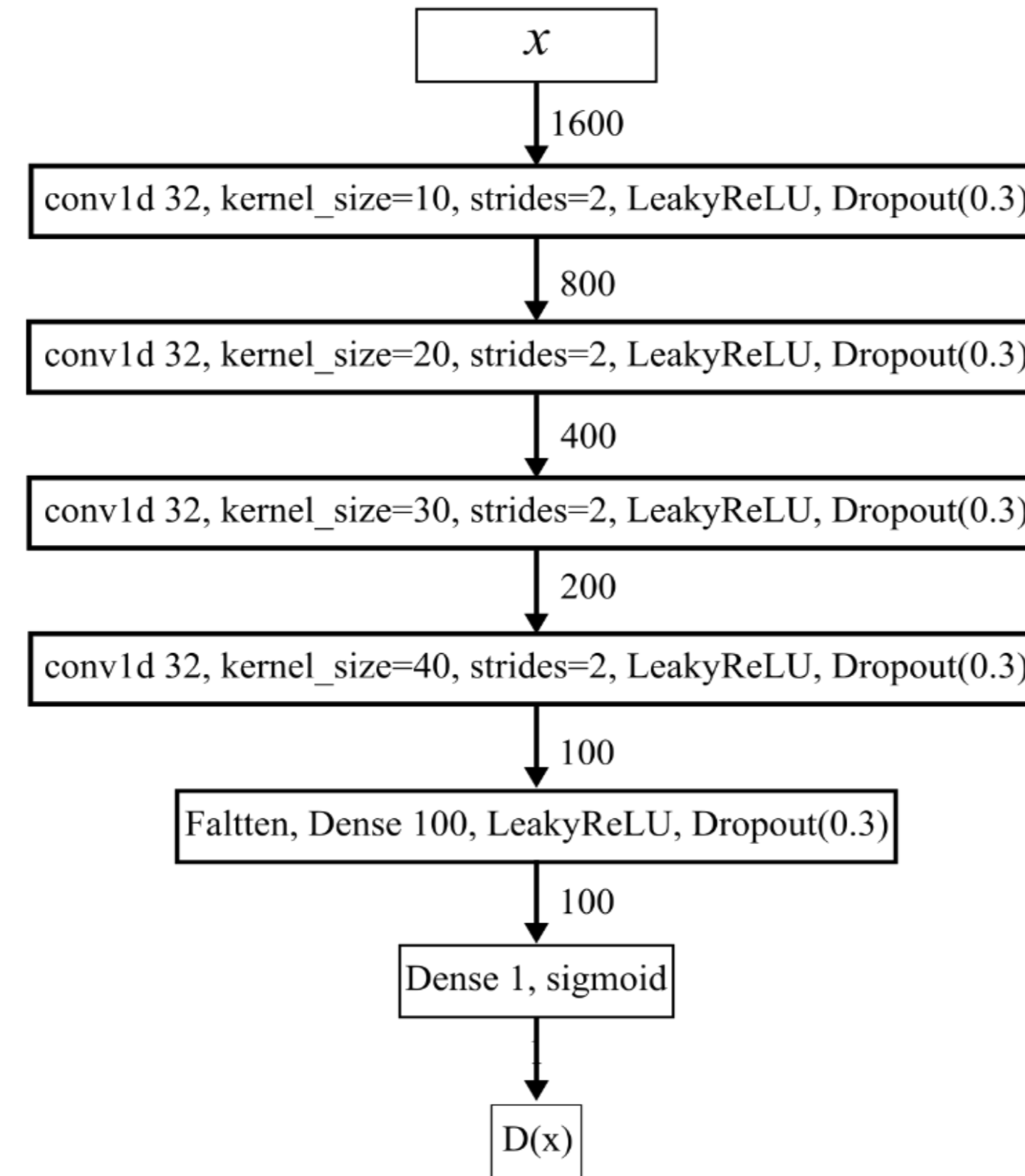
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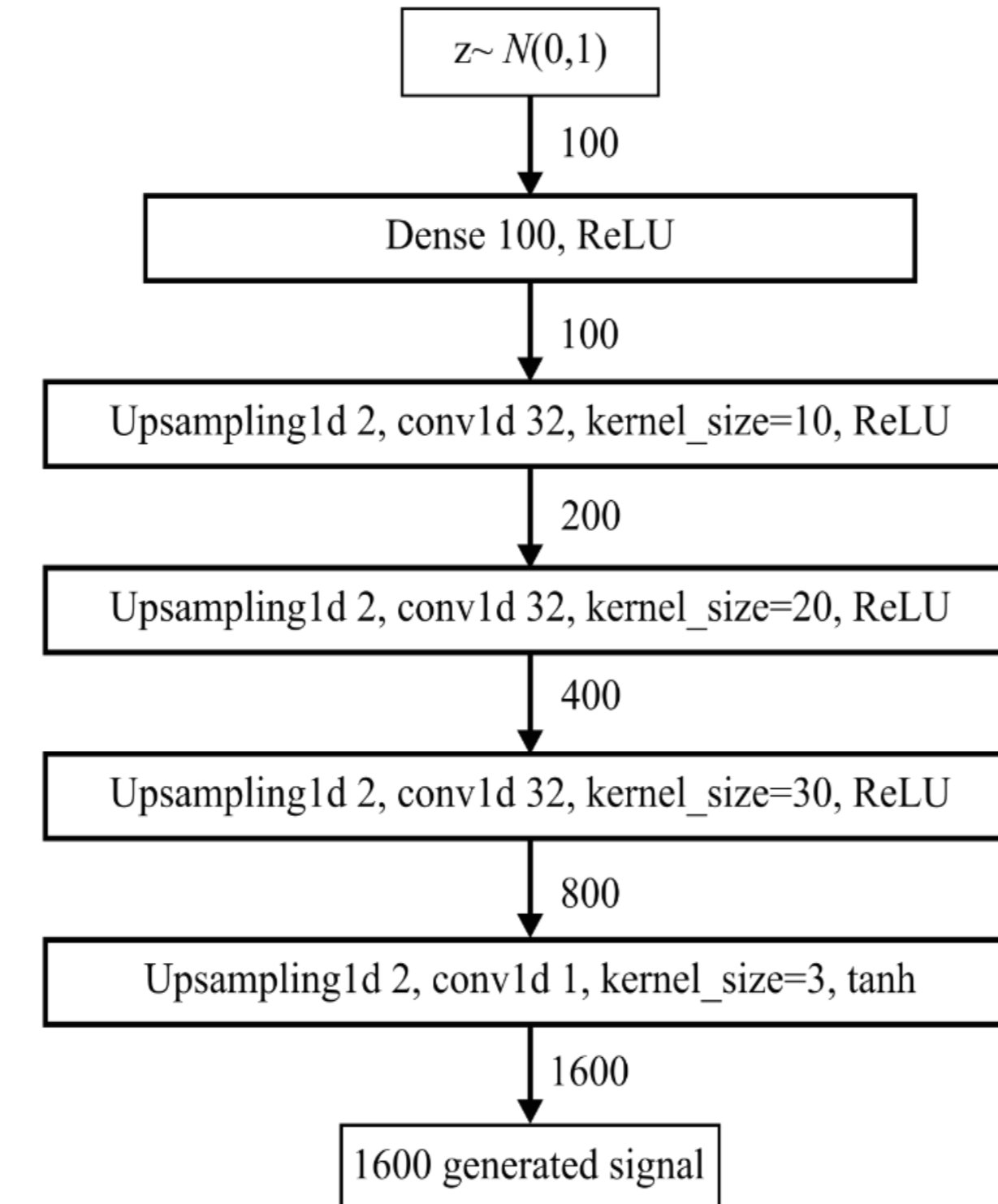
FID Threshold: 5 x 1E-5



4. Discriminator Architecture



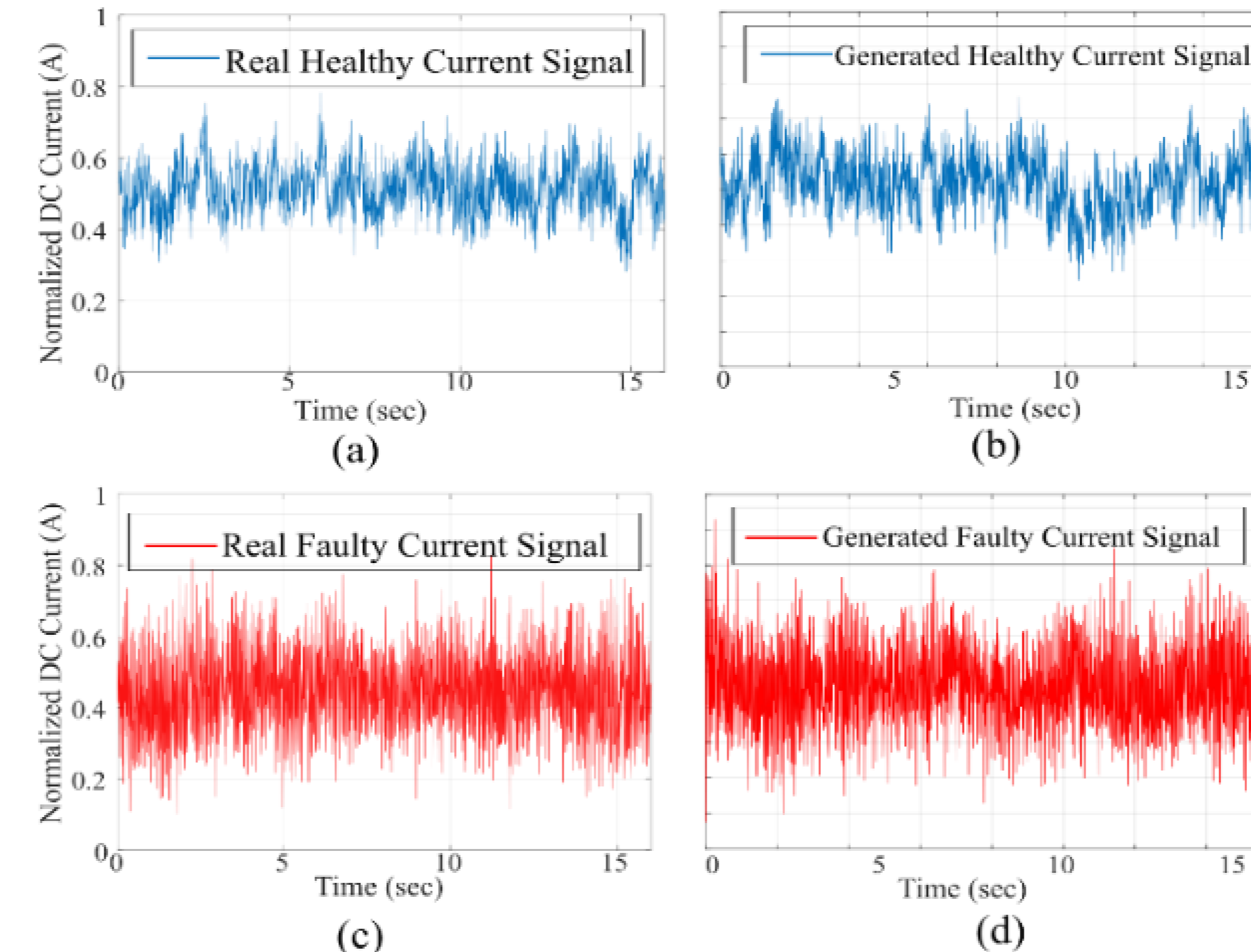
5. Generator Architecture



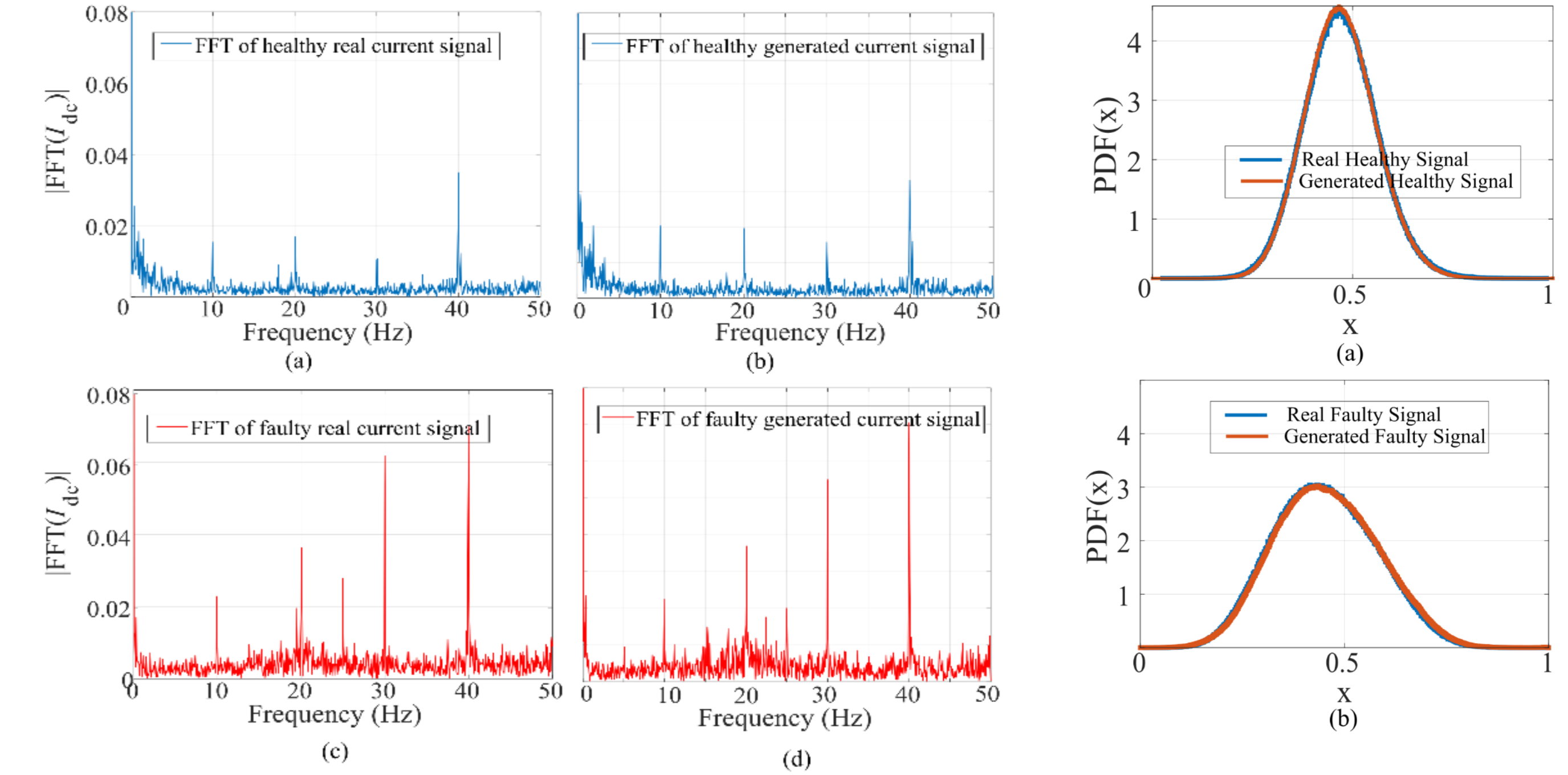
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7. Generated Data



8. Results Evaluation using FFT and PSD



9. Further Evaluation of Results

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where, $p_i = |C_i| / \sum_{n=1}^m |C_n|$
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 $|C_i|$ is the number of signals in the cluster where $i = 1, \dots, m$

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