

# **Background Invariance by Adversarial Learning**

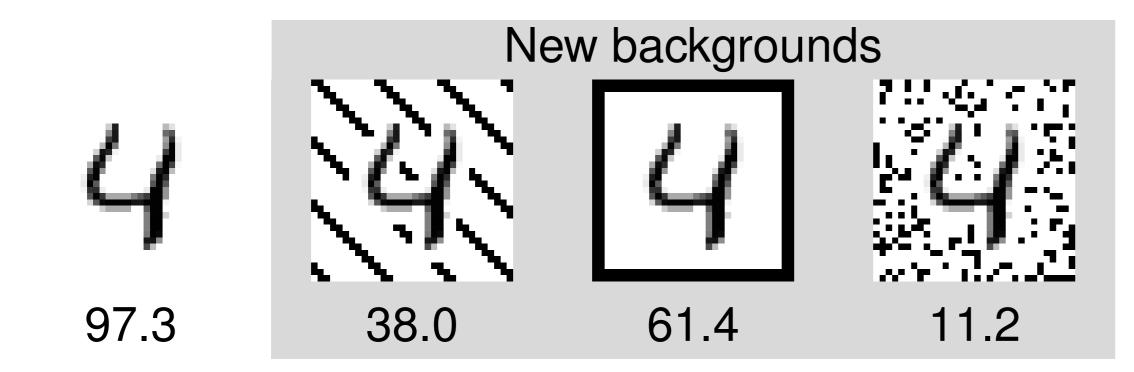
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### Motivation

CNNs fail to distinguish foreground (object) from background.
Notice how a model with accuracy of 97.3% can drop to as low as 11% (random) just by changing the background.



- The goal is to (during training) be able to place the object in a multitude of contexts (backgrounds).
- Focus on "what" the object is rather than "where" the object is.
- The backgrounds are generated in an adversarial manner.
- However, the insertion of adversarial backgrounds in the image cannot be allowed to destroy the concept (class) one is trying to learn.
- **A model** *f* is optimized to minimize a loss  $\mathcal{L}(y, f(x))$ .
- -A mask generator f<sub>m</sub> is trained to produce a mask m̂ ∈ [0, 1].
  \* This U-Net is trained unsupervisedly by finding the best mask that minimizes the previous loss, L (f(x ⊙ f<sub>m</sub>(x)), y).
  -A background generator f<sub>b</sub> transforms noise z into a background b̂ image.

Figure 1: Accuracy (%) of vanilla CNN trained for MNIST.

## **Related Work**

Little literature exists on making CNNs background invariant. One work proposes **an attention mechanism** to avoid artifacts, particularly irregular borders [1].

- Two classifiers: a *global* CNN *G*, and a *local* CNN *L*.
- *G* is trained to classify the entire image *x*.
- A activation maps from a truncated  $G^T$  are then used to find a bounding box of the object and crop x'.
- *L* is then trained using the smaller x'



\* The trick: it (adversarially) maximize the loss  $\mathcal{L}$ .

**Summary:** Model *f* tries to *minimize* a loss while  $f_b$  tries to find backgrounds that *maximize* it:

 $\min_{f,f_m} \max_{f_b} \sum_{i=1}^N \mathcal{L}\left(f\left(\hat{m}_i \odot x_i + \hat{b}_j \odot (1 - \hat{m}_i)\right), y_i\right).$ 

This is inspired by literature in adversarial training and GANs.



(a) t = 1 (b) t = 10 (c) t = 20 (d) t = 30 (e) t = 40Figure 4: Background augmentation along the epochs.

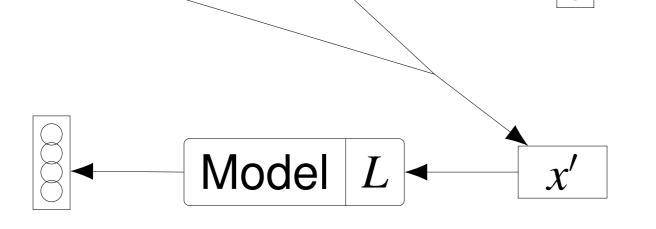


Figure 2: Attention mechanism diagram.

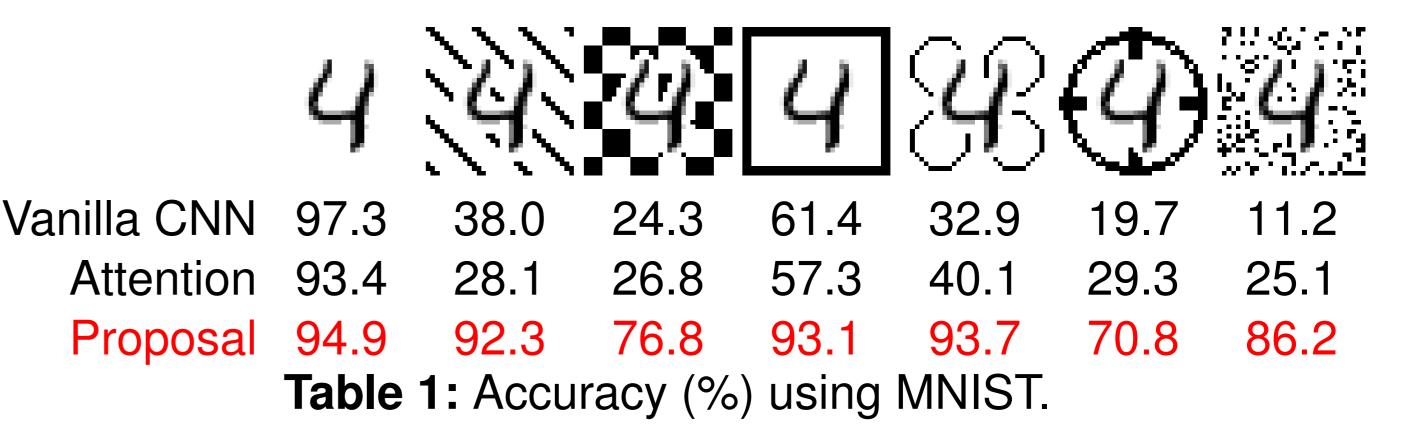
Two disadvantages are immediate:

- i. *L* operates on a rectangular cropped version of the image and therefore is still influenced by artifacts that remain inside that rectangle.
- ii. Model *G* is still influenced by artifacts because it did not have the benefit of being trained against the artifacts. While such artifacts are not presented in the training set, they could be generated in a controlled fashion, as our method now proposes:

#### **Proposed Method**

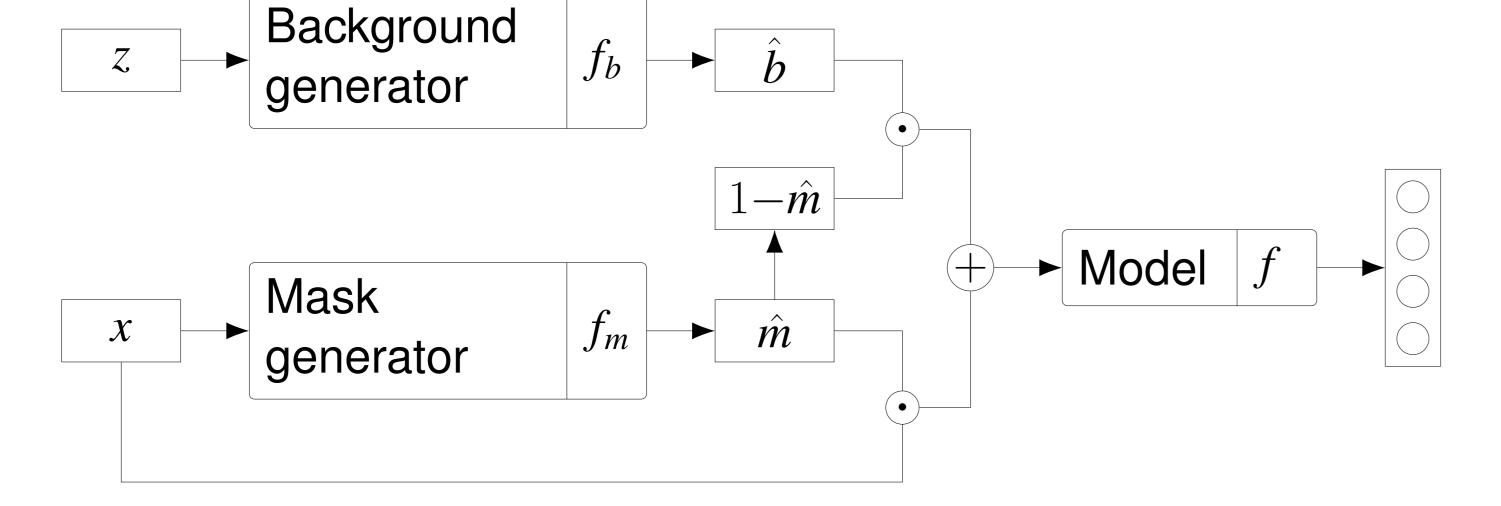
#### **Experiments**

- The attention mechanism only negligibly improves on the baseline classifier.
- The proposed method is resilient to a wide range of testing backgrounds.



### Conclusion

• Sometimes it is easier to collect data inside a studio rather than



in the real world – for example when training a drone. Unfortunately, a CNN does terrible when used in new backgrounds.
An adversarially trained data augmentation method is proposed. The proposed method can be used for classification,

References

regression, segmentation, reinforcement learning, etc.

#### Figure 3: Proposed method.

[1] Qingji Guan, Yaping Huang, Zhun Zhong, Zhedong Zheng, Liang Zheng, and Yi Yang. Diagnose like a radiologist: Attention guided convolutional neural network for thorax disease classification. *arXiv preprint arXiv:1801.09927*, 2018.

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