Conditional-UNet: A Condition-aware Deep Model for Coherent Human Activity Recognition From Wearables

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Triaxial Left lean accelerometer Head up Triaxial Right lean gyroscope Head dow Acc X Acc Y Acc Z Right Gyro X Gyro Y Gvro Z

(a) Right-roll under sit

(b) Right-roll under walk

A novel condition-aware deep model called "Conditional-UNet"

Challenges

- (1) The single location of sensors has mutual impact on signals.
- (2) The imbalanced domination of different activities could fade away the signals of the other activities.
- (3) The multi-label window problem for activities of various duration.

Deep architectures for a new encoding module



down

Limitations:

Real-life scenarios are more complicated. Need to include more deep learning methods to compare.

We run deep models on desktop GPU, but computation power is constrained in real-world wearables.

Future works

Is such trained model transferred for realworld scenario? Or need re-training? In the data likelihood loss, hierarchical labels can be considered or imbalanced class problem can be studied in the future.

A more general likelihood estimation

Raw data likelihood formula

 $p(Y_1,\ldots,Y_H|X) =$ Yi: different labels $p_{\theta_1}(Y_1|X)p_{\theta_2}(Y_2|Y_1,X)\dots p_{\theta_H}(Y_H|P_{H-1},\dots,Y_1,X)$ X: sensors data

> Our approach: Conditional data likelihood factorization as a more general framework

$$\mathcal{L} = log(p(Y_1, \dots, Y_H | X)) = \sum_{t}^{i} \left(log(p_{\theta_1}(Y_{1,t} | X)) + \dots + log(p_{\theta_H}(Y_{H,t} | P_{H-1,t}, \dots, Y_{1,t}, X)) \right)$$
(2)

True Head Labe

Predict Head Labe

True Walk/Sit

Predict Walk/Sit

Existing approaches: multi-label classification assuming conditional independences

 $p(Y_1, \ldots, Y_H | X) = p_{\theta_1}(Y_1 | X) p_{\theta_2}(Y_2 | X) \ldots p_{\theta_H}(Y_H | X)$

Experiment results

right-roll

right-lean

left-roll

Baseline models:

SVM, UNet Two alternatives of Conditional-Unet: (1) DWcoDH. Walking

