# TRACKING FAST MOVING OBJECTS BY SEGMENTATION NETWORK <br> Zita, A., Šroubek, F. <br> Institute of Infomation Theory and Automation <br> Czech Academy of Sciences 

## World of Fast Moving Objects

A (F) ast (M)oving (O)bject is loosely defined as an object traveling the distance larger than its size in a single video frame or image.
FMO appears as a blurred streak in the direction of motion
Tracking FMOs is a challenging problem due to lack of any texture on the blurred object.


## Goal:

Real-time tracking algorithm of balls in sports videos where the balls undergo motion characteristic for FMOs. $\rightarrow$ Learning-based approach (segmentation neural network)

## Synthetic data generator

o train the network, a synthetic-data generator synthesizes the data on the fly . YouTube sport videos were filtered using the median filter to erase any unwanted FMOs. These sequences are used as a background for synthetic data.
2. Motion-trajectory generator simulates plausible motion and creates synthetic trajectories
3. Trajectories are split into individual frame
Finally, the generated trajectories are convolved with the foreground (ball) and alpha-blended with the background to generate realistic FMOs.

Given that
$I_{t}(\mathrm{x})$ - composed image
$P_{t}(x)$ - generated path;
$b_{f}$ - overexposure factor;
$F(x)$ - foreground image (ball);
$M(x)$ - foreground image mask;
$B(x)$ - background image
The image synthesis can be described using following formula


$$
I_{t}(x)=\left[P_{t} * b_{f} F\right](x)+\left(1-\left[P_{t} * M\right]\right) B(x)
$$



## Method

The proposed solution is based on the U-Net Inception type network called ENet trained on synthetic data. The network input is a 15 -channel image consisting of 5 consecutive RGB frames. The resulting output is a segmentation map of the FMO


5x3ch image


## Tracking

The output of the network is a segmentation map with false positives. The mos probable blob is identified using blob size and shape heuristics. The selected blob is used as a trajectory estimation for the tracker. Kalman filter is used for prediction and connection of broken trajectories.


Path generator


