

# 2D License Plate Recognition based on Automatic Perspective Rectification

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# Introduction

## ◆ License Plate Recognition(LPR)



- The plates in the images are likely to be distorted due to shooting angles, which directly affect the recognition of license number.
- License plates(LPs) include many kinds, varying in background color, length of numbers and character arrangement. The diversity of Chinese LPs is a challenge to LPR. The numbers consists of Latin letters, digit and Chinese characters.

# Motivations

## ◆ Existing LPR methods



(a) Character-based



(b) RNN-based

Existing LPR methods can be roughly categorized into two groups: character-based and RNN-based.

- **Character-based** methods relies on character segmentation, which is unreliable to illumination, pose and noise in the image.
- **RNN-based** methods can only recognize plates with no or minimal deformations.

# Motivations

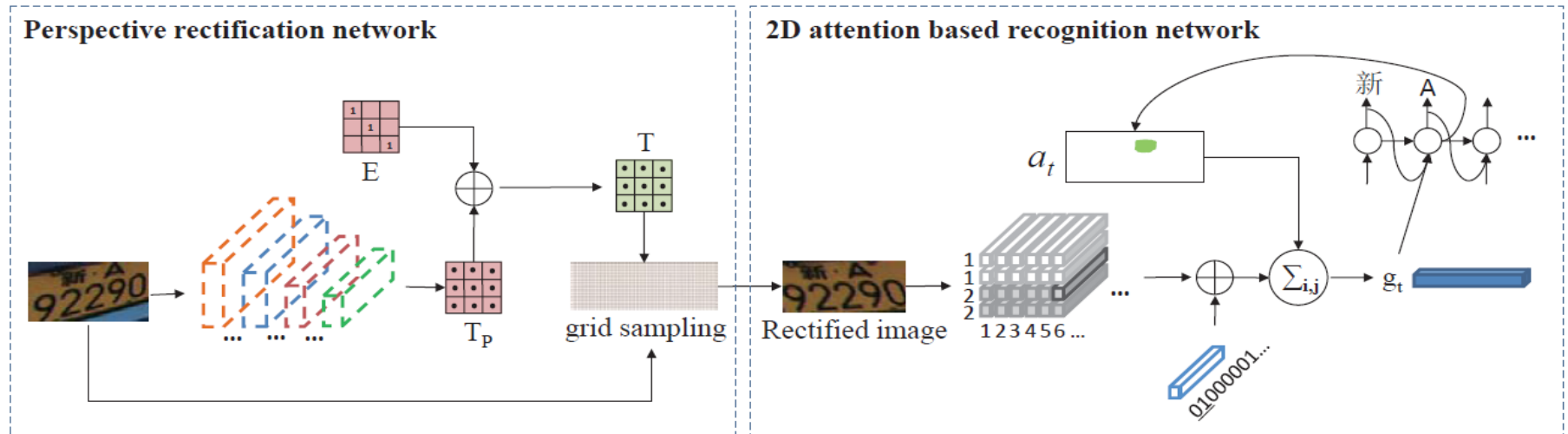
## ◆ Existing Irregular text recognition methods



- A text rectification module is always designed for irregular text recognition. However, the universal text rectification methods are designed for various irregular text, which can not achieve good effectiveness in LPR.
- LPs can **only produce perspective deformation** in the image due to its rigid body property.

✓ we propose a novel method consisting of a novel perspective rectification network (PRN) and a location-aware 2D attention based recognition network for the LPR task.

# Proposed Method



- **Perspective rectification network (PRN)** estimates the perspective transformation of an input LP image automatically and generates the rectified LP image.
- **2D attention based recognition network** identify both single-line and double line LPs with 2D attention mechanism.

# Proposed Method

## ◆ Perspective rectification network (PRN)

PRN includes two steps: perspective transformation prediction and grid sampling.

TABLE I  
ARCHITECTURE OF PERSPECTIVE RECTIFICATION NETWORK

Layer Name	Configurations	Size
Input	-	$1 \times 32 \times 100$
Convolution	c:64, k: $3 \times 3$ , s: $1 \times 1$ , pad:1	$64 \times 32 \times 100$
MaxPooling	k: $2 \times 2$ , s: $2 \times 2$	$64 \times 16 \times 50$
Convolution	c:128,k: $3 \times 3$ , s: $1 \times 1$ , pad:1	$128 \times 16 \times 50$
MaxPooling	k: $2 \times 2$ , s: $2 \times 2$	$128 \times 8 \times 25$
Convolution	c:256,k: $3 \times 3$ , s: $1 \times 1$ , pad:1	$256 \times 8 \times 25$
MaxPooling	k: $2 \times 2$ , s: $2 \times 2$	$256 \times 4 \times 12$
Convolution	c:512,k: $3 \times 3$ , s: $1 \times 1$ , pad:1	$512 \times 4 \times 12$
AvgPooling	k: $2 \times 2$ , s: $2 \times 2$	$512 \times 1 \times 1$
fc1	256	256
fc2	9	9

*c,k,s,pad represent channel,kernel, stride and padding sizes respectively.*

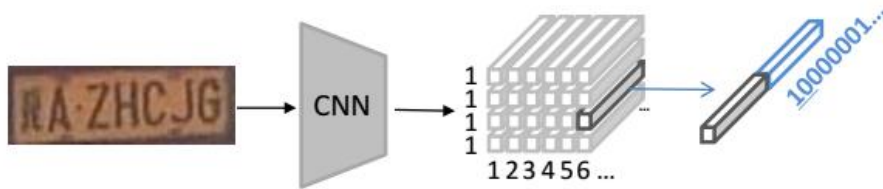
- **Perspective transformation prediction:**

The rectification network directly predicts an offset matrix  $\mathbf{T}_p$ , and the perspective transformation  $\mathbf{T}$  is calculated.

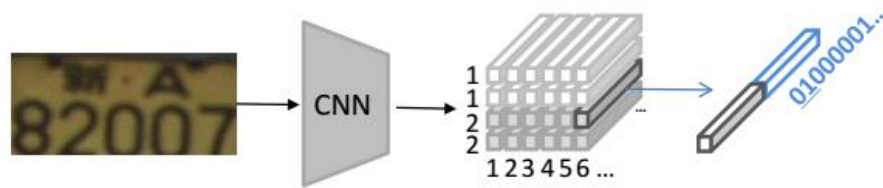
- **Grid sampling:** The sampling grid is generated by  $\mathbf{T}$  and properties of perspective transformation.

# Proposed Method

## ◆ 2D attention based recognition network



(a) Single-line LP



(b) Double-line LP

- 2D attention mechanism is adopted to predict license numbers sequence directly from the 2D feature maps.
- the one-hot encoding of the simplified spatial coordinates is used to make  $\alpha_t$  sensitive to single-line or double-line.

$$r_j = \begin{cases} 1, & \text{single-line} \\ \left\lfloor \frac{j}{2} + 0.5 \right\rfloor, & \text{double-line} \end{cases}$$



$$H = W_h h_{i,j} + W_s s_{t-1} + W_i f_i + W_{r_j} f_{r_j} + b$$



$$e_{t,i,j} = V_a^T \tanh(H)$$

$$\alpha_{t,i,j} = \frac{\exp(e_{t,i,j})}{\sum_{i,j} (\exp(e_{t,i,j}))}$$



# Experiments

## ◆ Datasets

- **Synthetic data** are generated randomly with various brightness, chroma, clarity and angles of view.
- **CLPD** dataset contains about 260,000 Chinese single-line LPs collected from different security and surveillance cameras
- **CCPD** is collected in the parking lot of Hefei province of China.
- **DLTD** is a private double-line plates dataset collected from surveillance cameras of traffic crossroads.
- **SYSU-ITS** dataset is a public LP image set, which is provided by OpenITS.



(a) Synthetic data



(b) CLPD



(c) CCPD



(d) DLTD



(e) SYSU-ITS



# Experiments

## ◆ Rectification module

- The ablation study is carried out to validate the performance gain of the rectification component.
- The rectified LP images of different rectification methods are shown to validate the visualization performance of PRN.

TABLE II  
PERFORMANCE OF RECTIFICATION MODULE

Rectification	Recognition	CLPD	T-CCPD
NULL	2D-Attn	98.12%	72.72%
TPS[10]		98.33%	80.78%
MORN[11]		98.22%	74.27%
PRN (ours)		<b>98.5%</b>	<b>82.2%</b>

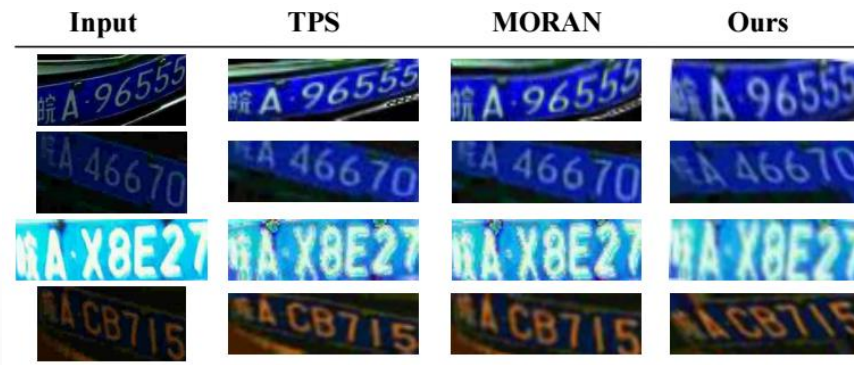
















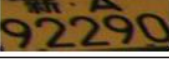
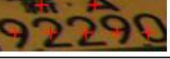








Fig. 4. Rectified images generated by different methods.

# Experiments

## ◆ Recognition module

Input	Method	Rectified Image	Attention Output	Prediction
 皖A0J201	Baseline			A0J2D1
	2d-Attn	-		苏A0J201
	Ours			皖A0J201
 皖AZ2Z46	Baseline			豫AZ224G
	2d-Attn	-		1AZ2Z4G
	Ours			皖AZ2Z46
 新A92290	Baseline			92290
	2d-Attn	-		新A92290
	Ours			新A92290
 HEHE HAHA	Baseline			HAHA
	2d-Attn	-		HEHEHAHA
	Ours			HEHEHAHA

- The recognition module performs well on both single-line and double-line plates.
- The overall model is improved by the perspective rectification module and location-aware attention.

TABLE III  
PERFORMANCE OF RECOGNITION MODULE, WHERE RECT. REPRESENTS RECTIFICATION MODULE.

Rect.	Recognition	CLPD	T-CCPD	D-SYSU
-	1D-Attn [10]	97.4%	59.7%	87.72%
	2D-Attn [34]	98.12%	72.72%	93.8%
LPRNet[8]		97.3%	67.41%	-
Yu [18]		94.5%	68.4%	89.1%
Baseline [10]		97.71%	79.26%	90.4%
Ours		<b>98.7%</b>	<b>83.1%</b>	<b>94.2%</b>

# Conclusions

- ◆ We have proposed a novel 2D license plate recognition method based on automatically perspective rectification for LPR.
- ◆ We have improved the recognition performance of the license plates with heavy deformations in the images.
- ◆ In the future work, the LP detection and the model efficiency are the pivotal research.

**THANK YOU !**