

Scalable Direction-Search-Based Approach to Subspace Clustering

Yicong He and George K. Atia

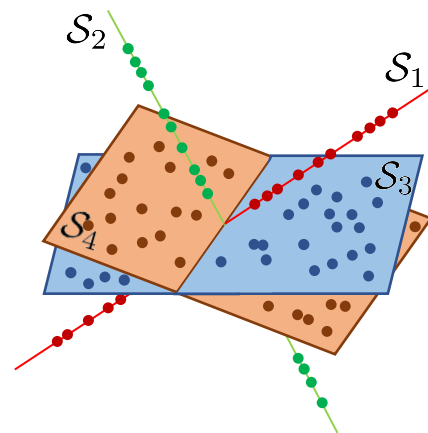
Department of Electrical and Computer Engineering, University of Central Florida

Yicong.He@ucf.edu, George.Atia@ucf.edu

Subspace clustering

Data \mathbf{X} lies in a union of low-dimensional subspaces $\cup_{i=1}^k \mathcal{S}_i$

The goal of subspace clustering : Grouping data belonging to the same subspace (cluster).



Representation-based subspace clustering

$$\min_{\mathbf{C}} \|\mathbf{X} - \mathbf{XC}\|_F^2 + f(\mathbf{C}), \text{ s.t. } \text{diag}(\mathbf{C}) = 0$$

$f(\mathbf{C}) = \|\mathbf{C}\|_1$ Sparse Subspace Clustering (SSC) [Elhamifar and Vidal, 2009]

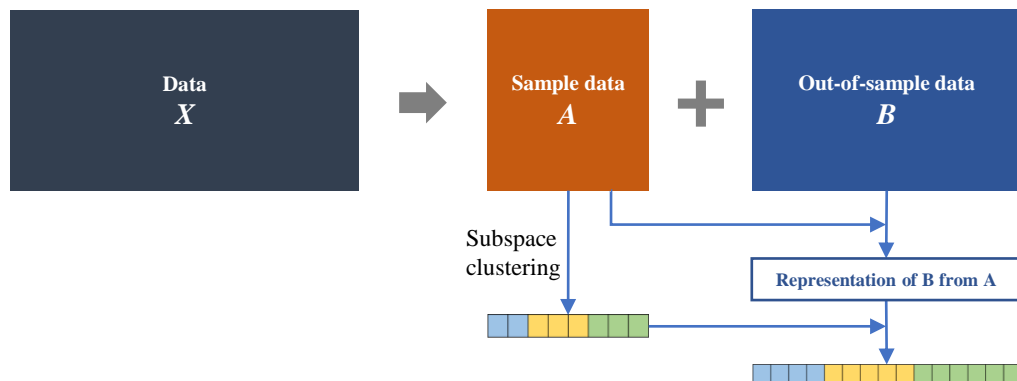
$f(\mathbf{C}) = \|\mathbf{C}\|_*$ Low Rank Representation (LRR) [Liu et al., 2012]

$f(\mathbf{C}) = \|\mathbf{C}\|_F^2$ Least Square Regression (LSR) [Lu et al., 2012]

*Find self-representation on the **whole** data*

Large-scale Subspace clustering

Scalable Framework for Representation-based subspace clustering [Peng et al., 2016]



Elastic Net Subspace Clustering (EnSC) [You et al., 2015]

Landmark-based Clustering (LSC) [Cai and Chen, 2015]

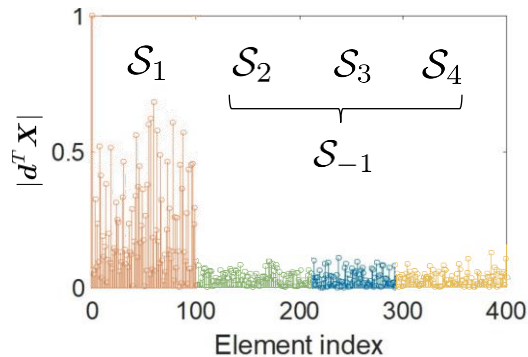
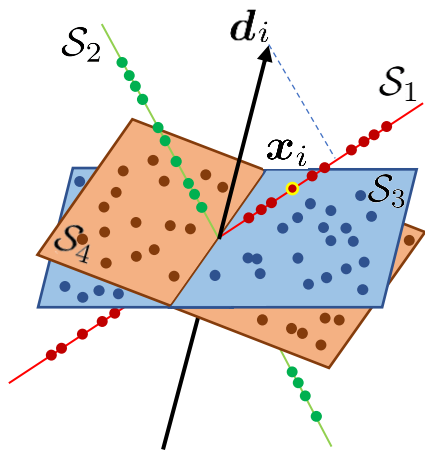
Scalable and robust SSC (SR-SSC) [Abdolali et al., 2019]

*Find self-representation on **a small subset of data***

Optimal Direction Search [Rahmani and Atia, 2017]

$$\min_{\mathbf{d}} \|\mathbf{d}^T \mathbf{X}\|_p \quad \text{s.t.} \quad \mathbf{d}^T \mathbf{x}_i = 1$$

It searches for an optimal direction $\mathbf{d}_i \in \mathbb{R}^{M \times 1}$ for each data point \mathbf{x}_i by minimizing its projections on all data points except \mathbf{x}_i

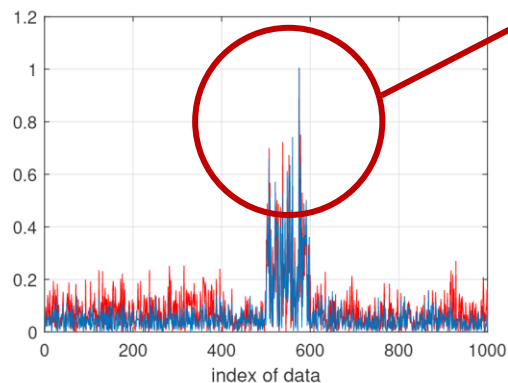
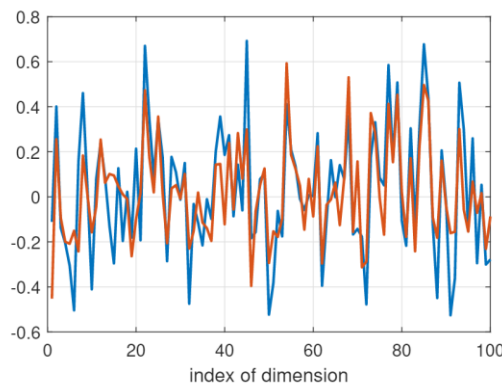


Large coherence with data in the same subspace

*Find directions on the **whole** data*

Do we need to compute the direction using all the data?

Use subset \hat{X} $\hat{d}_i = \arg \min_d \|d^T \hat{X}\|_p$ s.t. $d^T \hat{x}_i = 1$



Coherence is highly preserved

Computed d_i, \hat{d}_i (left) and corresponding $|d_i^T X|, |\hat{d}_i^T X|$ (right) using full data (blue) and 20% of the data (red)

Find directions on a small subset of data

Also, the direction search is friendly to out-of-sample data...

For a data point b_i , its cluster label can be obtained using $|b_i^T D|$

Theoretical analysis

Proposition.1 Defining $\mathbf{d}_{op} = \arg \min_{\substack{\mathbf{d}^T \mathbf{x} = 1 \\ \mathbf{x} \in \mathcal{S}_j}} \|\mathbf{d}^T \mathbf{X}\|_1$, if the following conditions are satisfied

- (1) $\sum_{\mathbf{x}_i \in \mathbf{X}^{-j}} |\mathbf{v}^T \mathbf{x}_i| + \sum_{\substack{\mathbf{x}_i \in \mathbf{X}^j \\ i \in I_0}} |\mathbf{v}^T \mathbf{x}_i| > \sum_{\mathbf{x}_i \in \mathbf{X}^j} \text{sgn}(\mathbf{x}_i^T \mathbf{d}_{op}) \mathbf{v}^T \mathbf{x}_i$ $I_0 = \{i \in [n_j] : \mathbf{x}_i^T \mathbf{d}_{op} = 0, \mathbf{x}_i \in \mathbf{X}^j\}$
 \mathbf{v} —an arbitrarily small vector satisfying $\mathbf{v}^T \mathbf{x} = 0$
- (2) $\mathcal{S}_j \not\subseteq \mathcal{S}_{-j}, j \in [k]$
- (3) $M \gg r_j, j \in [k]$ M —ambient dimension r_j —dimension of \mathcal{S}_j

Then we have $\mathbf{d}_{op} \in \mathcal{S}_{-j}^\perp \iff \boxed{\mathbf{d}_{op}^T \mathbf{X}^{-j} = \mathbf{0}}$

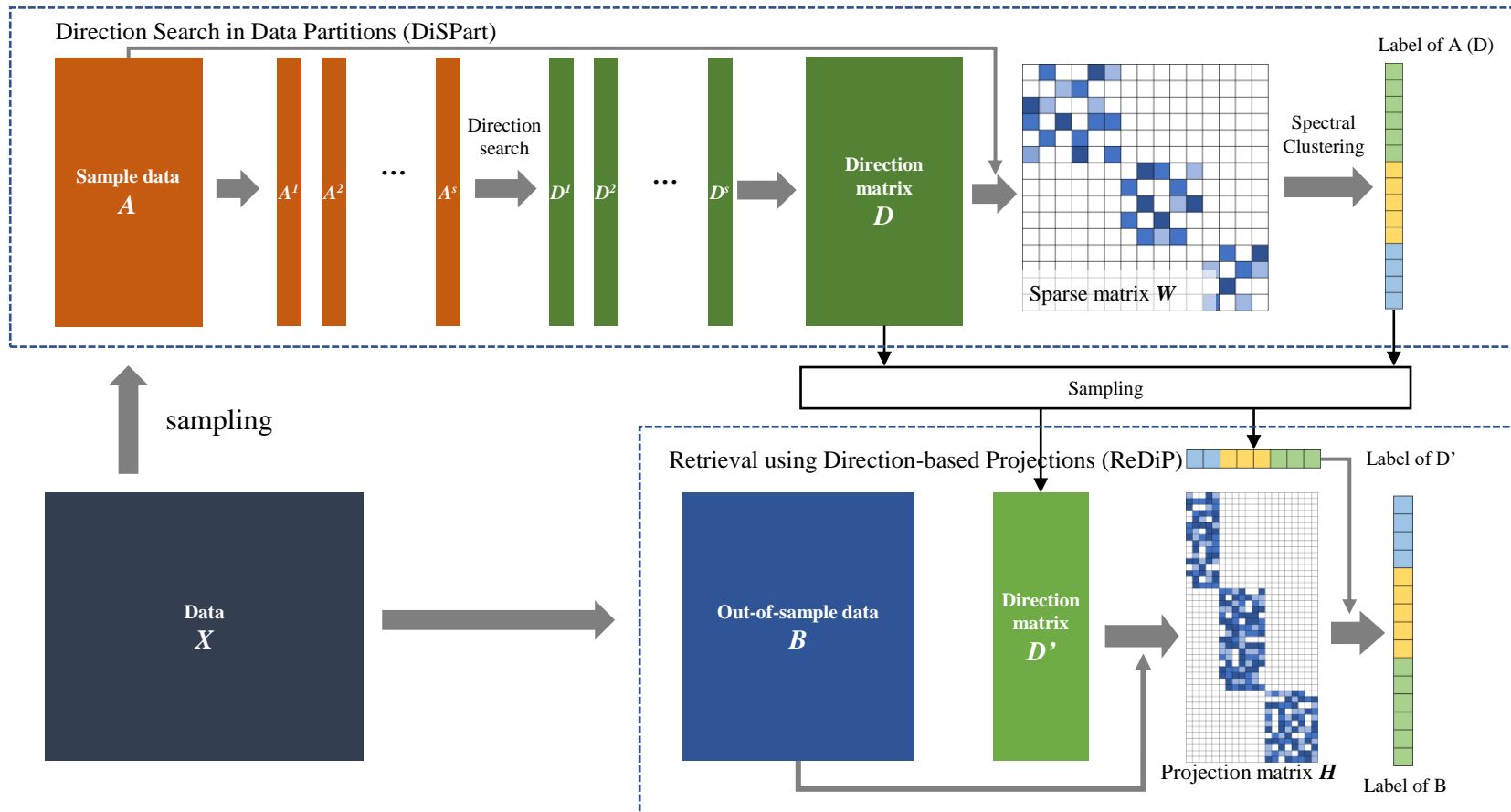
According to Theorem 1, for a subset $\hat{\mathbf{X}}$, we have

$$\hat{\mathbf{d}}_{op} = \arg \min_{\substack{\mathbf{d}^T \mathbf{x} = 1 \\ \mathbf{x} \in \mathcal{S}_j}} \|\mathbf{d}^T \hat{\mathbf{X}}\|_1 \implies \hat{\mathbf{d}}_{op}^T \hat{\mathbf{X}}^{-j} = \mathbf{0}$$

$$\begin{matrix} \mathbf{X}^{-j} = \hat{\mathbf{X}}^{-j} \mathbf{C}^{-j} \\ \text{self-representation} \end{matrix} \implies \boxed{\hat{\mathbf{d}}_{op}^T \mathbf{X}^{-j} = \hat{\mathbf{d}}_{op}^T \hat{\mathbf{X}}^{-j} \mathbf{C}^{-j} = \mathbf{0}}$$

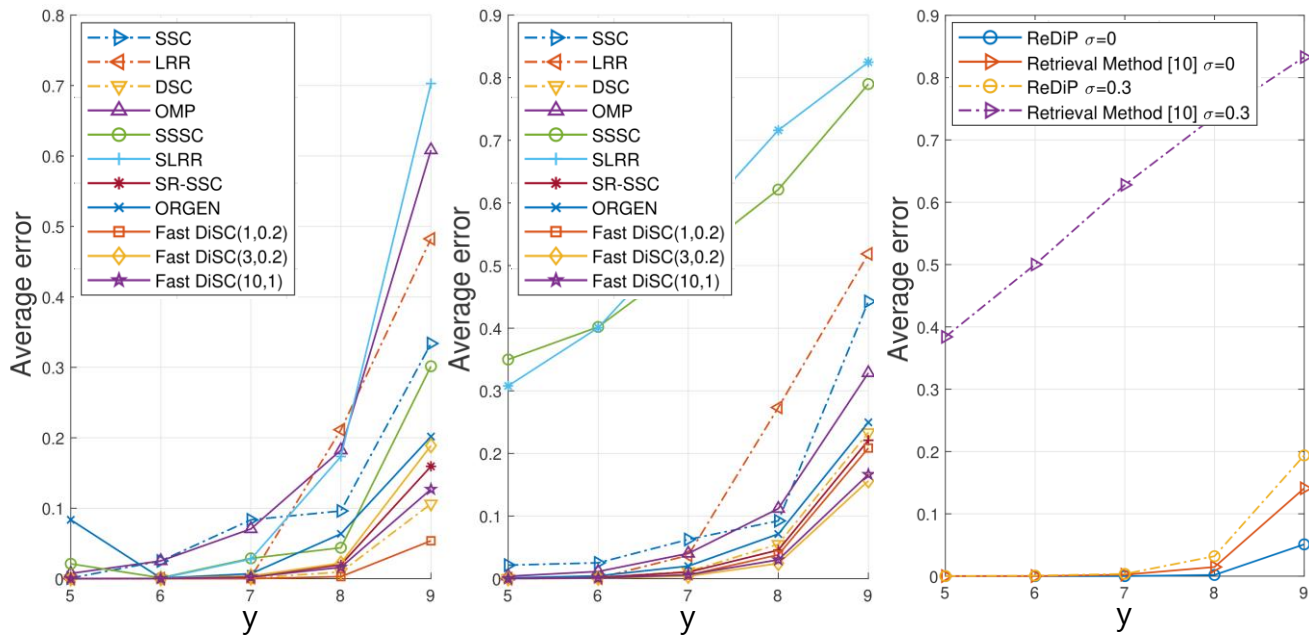
We can find correct neighborhoods with $|\hat{\mathbf{d}}_{op}^T \mathbf{X}|$

Framework of Fast Direction Search-Based Subspace Clustering (Fast DiSC)



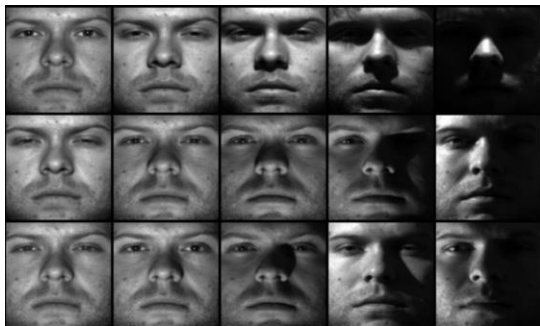
Experiment on synthetic data

\mathbf{X} lies in $\cup_{i=1}^k \mathcal{S}_i$ $\mathcal{S}_i = \mathcal{R}_i \oplus \boxed{\mathcal{M}}$ y -dimensional subspace shared by all subspaces



Average clustering error as function of the dimension of the intersection y . Left: noiseless ($\sigma = 0$) on whole process. Middle: noisy ($\sigma = 0.3$) on whole process. Right: Retrieval performance comparison only.

Experiment on real datasets



Extended Yale B

38 subjects
2432 images



USPS

10 subjects
9298 images



MNIST

10 subjects
70000 images

Experiment results on real Datasets

Dataset	Evaluation	OMP	SSSC	SLRR	SR-SSC	ORGEN	Fast DiSC ($s_1, \mathbf{0.2}$)	Fast DiSC ($s_2, \mathbf{0.5}$)	Fast DiSC ($s_3, \mathbf{1}$)	SSC	LRR	DSC
ExYale B	Acc(%)	71.90	59.67	56.43	71.03	60.90	50.48	78.00	90.30	67.59	73.43	91.89
	NMI(%)	79.31	66.22	67.60	76.84	70.95	58.97	79.82	92.20	73.08	83.11	93.53
	Time(s)	11.59	25.96	32.87	35.68	44.39	4.36	19.87	29.86	124.67	66.06	77.34
USPS	Acc(%)	19.77	45.18	47.82	66.62	48.92	70.01	74.17	77.53	48.56	55.77	64.70
	NMI(%)	6.87	52.47	52.48	68.02	56.70	69.77	73.11	78.24	58.77	61.79	78.59
	Time(s)	11.52	71.41	22.96	76.19	78.70	4.11	6.88	13.31	3881.29	385.80	1379.79
MNIST	Acc(%)	46.26	85.08	83.75	83.63	93.79	89.82	87.89	98.03	-	-	-
	NMI(%)	51.55	87.33	87.13	83.38	88.80	86.37	87.42	94.67	-	-	-
	Time(s)	695.41	713.47	194.37	1265.06	959.22	107.36	270.29	705.82	-	-	-

Fast DiSC(s, θ): s -number of partitions θ -sampling rate (i.e., $N_1 = \lfloor \theta N \rfloor$) in DiSPart

Summary of contribution of the work

- (1) **We develop Fast DiSC for large-scale subspace clustering**, which consists of two newly proposed procedures DiSPart and ReDiP.
- (2) **We provide theoretical analysis for direction search**, showing that a small part of the data generally suffices to identify correct neighborhood sets for the data points in their corresponding subspaces.
- (3) **We present experimental results with comparisons to state-of-the-art algorithms on both synthetic and real data**, demonstrating the superior performance of the Fast DiSC.

Thank you!