

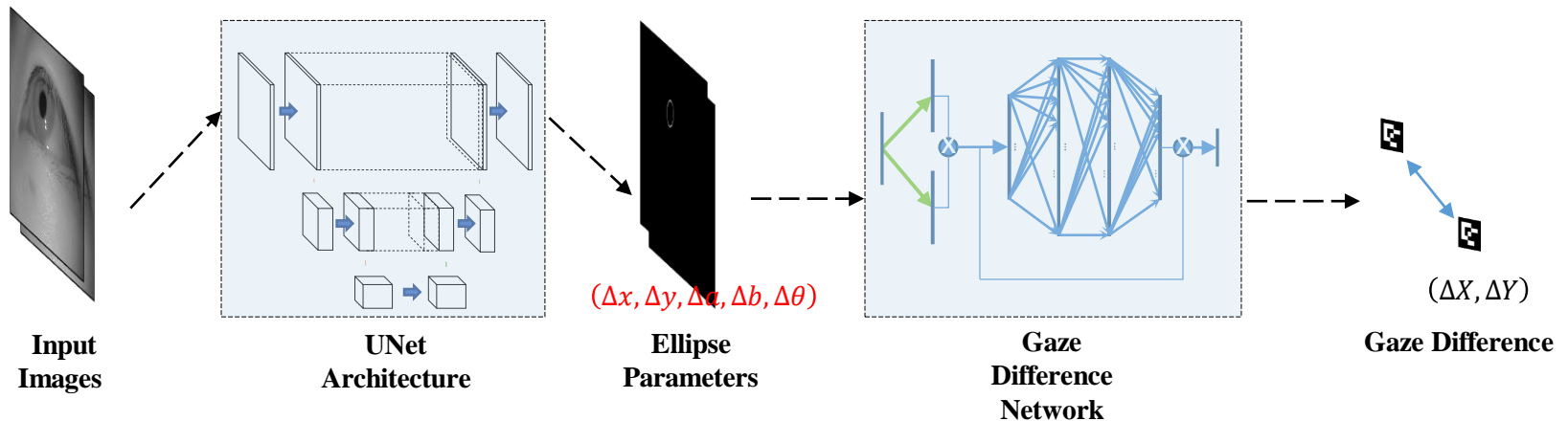
User-Independent Gaze Estimation by Extracting Pupil Parameter and Its Mapping to the gaze Angle

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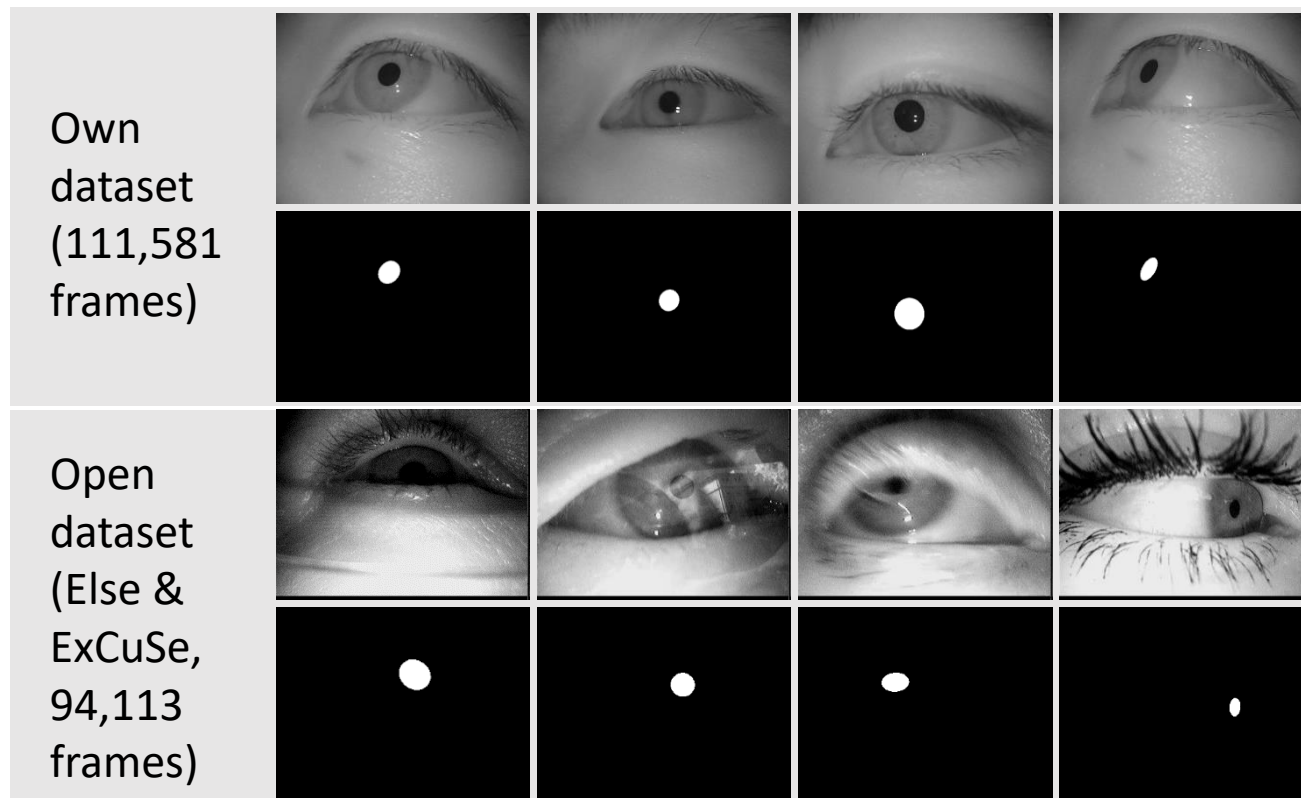
❖ Proposed Method

- Apply network(UNet) to frames for segment pupil candidate area.
- Confidence analysis to get frame with clear pupil area.
- Uses ellipse parameter acquired from pupil area to gaze difference network.
- Get gaze with using current frame and reference frame.



Pupil segmentation Dataset

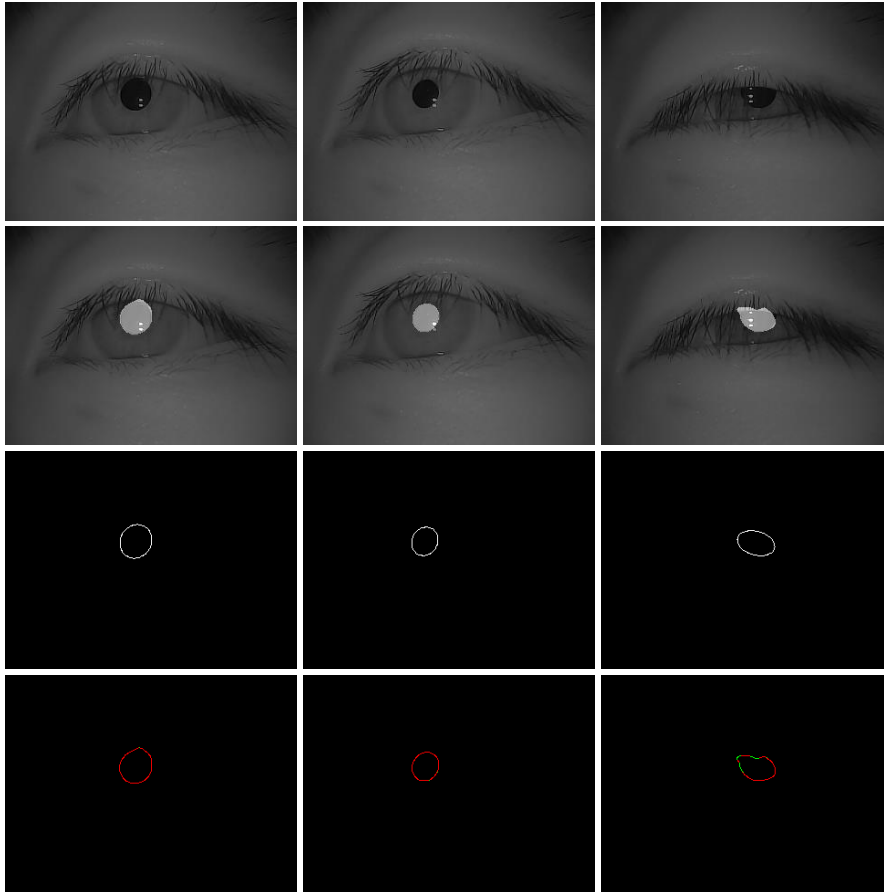
- ❖ Unlike the existing CNN-based pupil detection methods based on the regression, we use the CNN for the **pupil segmentation**.
 - ❖ Pupil boundary edges have more feature than pupil center.
 - ❖ Traditional methods finds pupil center from fitting ellipse using pupil edges.



← Only have center point

❖ Proposed Method

- Confidence analysis to get frame with clear pupil area.
 - The red pixel is the pixel belonging to the fitted ellipse
 - The green pixel is the pixel not belonging to the fitted ellipse



$$\rho = \sum_{p \in \Omega_o} S_p$$

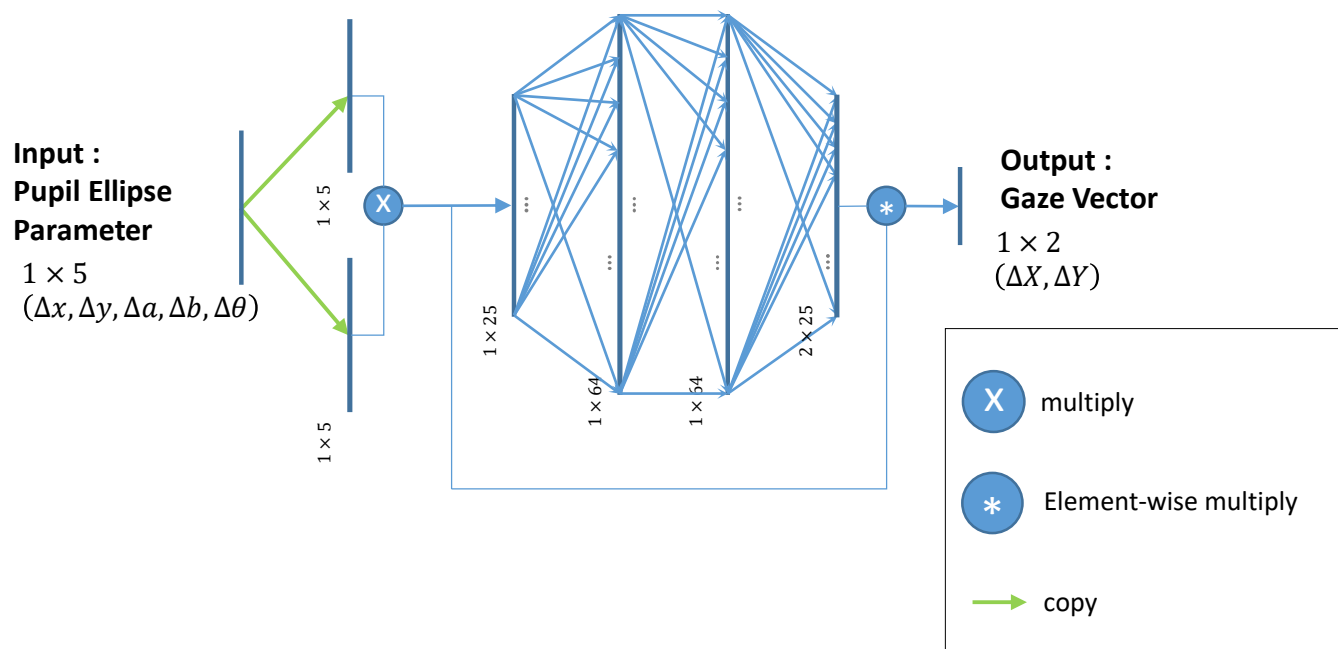
$$\phi = \frac{\sum_{p \in \Omega_{o_{edge}}} B^i}{\sum_{p \in \Omega_{o_{edge}}} 1}$$

$$\text{Confidence : } \varphi = \frac{\rho + \phi}{2} > 0.95$$

$$\text{where } B_{pqr}^i = \begin{cases} 1, & \text{if } p \in \Omega_{\text{Ellipse}} \\ 0, & \text{otherwise} \end{cases}$$

❖ Proposed Gaze Estimation Network

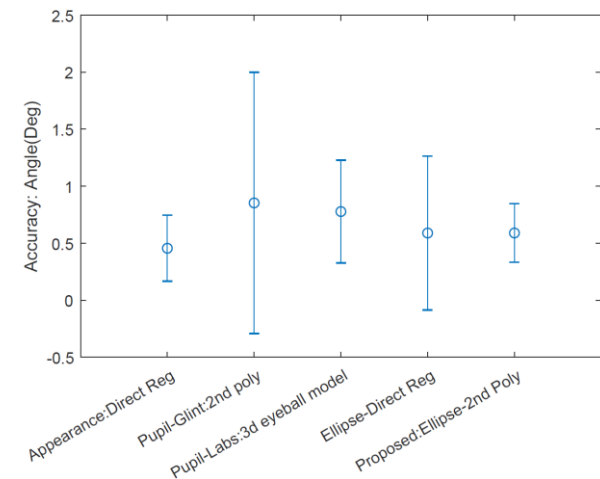
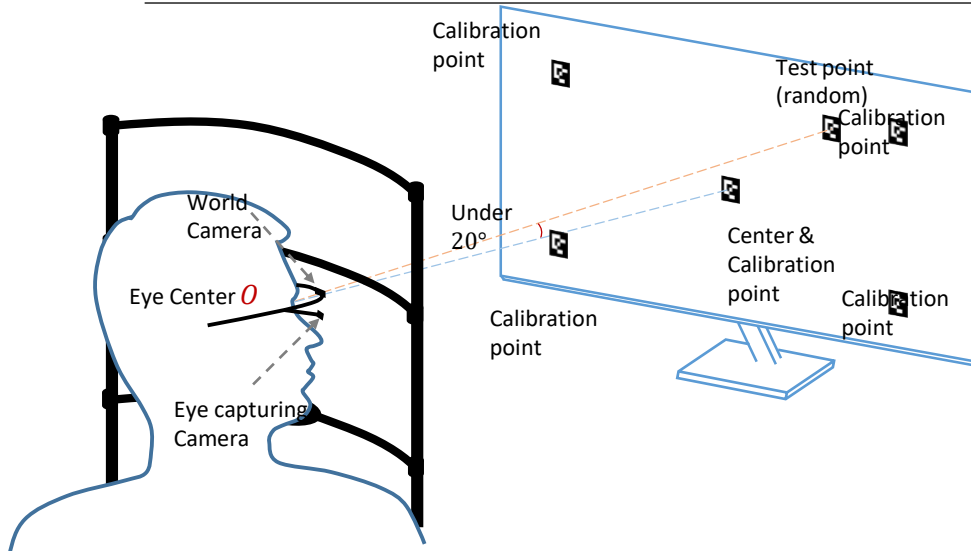
- Uses ellipse parameter difference acquired from reference frame and current frame
- Multiply input parameter twice in order to use the ellipse parameter of the pupil as the second polynomial variable.
- Result of passing the fully connected layer is to do the dot product with Equ.2 again before getting to the output.



❖ Experiment

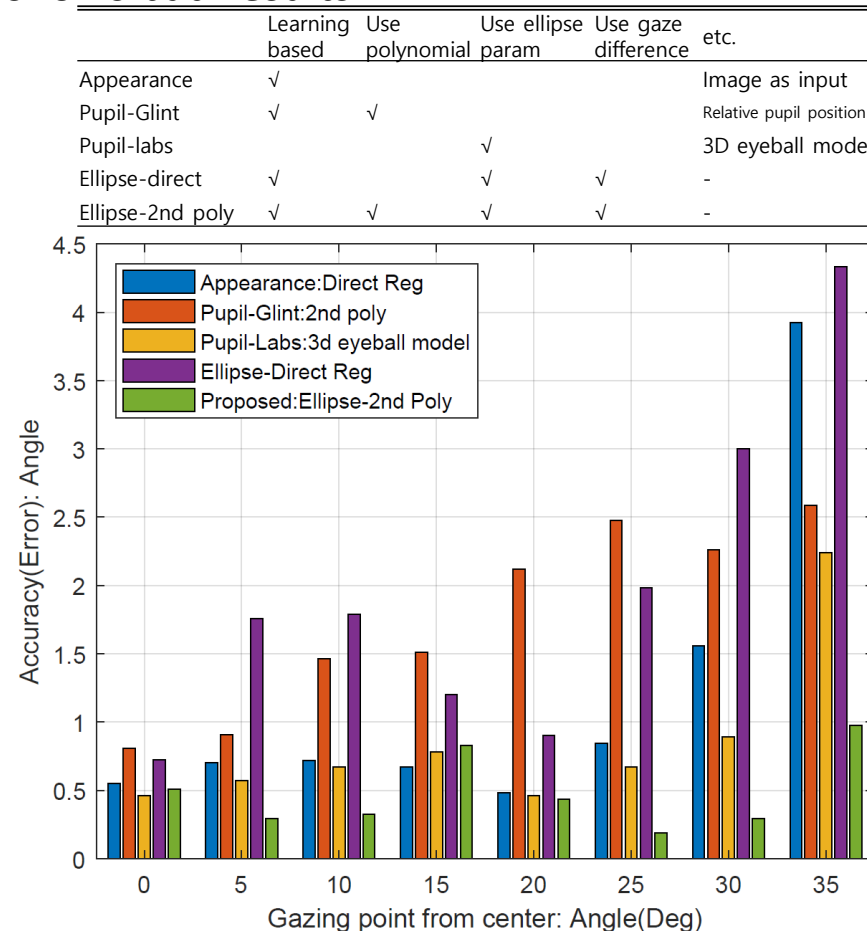
- The angular error in gaze detection on each users using using proposed algorithm. (unit: degree)
- Compute the error of the estimated gaze point and marker point position on the world camera while looking at the marker at each position of the monitor.
- Gazing points are composed of under 20 degree from center.

	User	User1	User2	User3	User4	User5	User6	User7	User8	User9	User10	User11	User12	User13	User14	User15	Average
Gaze Point	1	0.33	0.50	0.23	0.52	1.88	0.54	0.31	0.23	0.40	0.88	0.23	0.79	2.34	0.60	1.15	0.73
	2	0.32	0.13	0.12	0.13	0.40	0.21	0.25	0.32	0.31	0.92	0.13	0.78	2.38	0.66	1.22	0.55
	3	0.24	0.08	0.23	0.13	0.60	0.14	0.10	0.20	0.33	0.92	0.20	0.82	2.50	0.60	1.11	0.55
	4	0.22	0.19	0.33	0.14	0.75	0.31	0.29	0.25	0.34	0.87	0.12	0.78	2.32	0.65	1.23	0.59
	5	0.19	0.11	0.21	0.22	0.59	0.24	0.36	0.22	0.36	0.90	0.12	0.77	2.29	0.59	1.20	0.56
Average		0.26	0.20	0.23	0.23	0.85	0.29	0.26	0.24	0.35	0.90	0.16	0.79	2.37	0.62	1.18	0.59



❖ Experiment

- Results outside the calibrated range show quite different accuracy.
- Accuracy of networks that directly estimate X,Y coordinate of gaze over 20deg shows bad results



❖ Experiment

- Calibration Drift
- Recalibrating each time a calibration drift occurs makes user cumbersome
- Proposed method of using difference to minimize the calibration process when re-calibration.

