

# Generalized Shortest Path-based Superpixels for Accurate Segmentation of Spherical Images

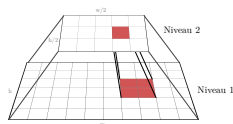
Rémi Giraud, Rodrigo Borba Pinheiro, Yannick Berthoumieu  
*remi.giraud@ims-bordeaux.fr*



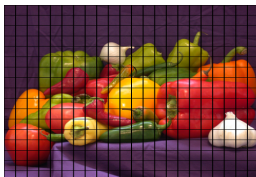
Bordeaux INP, Univ. Bordeaux, CNRS  
IMS, UMR 5218  
F-33400 Talence, France

Large data  $\rightarrow$  high computational times  $\rightarrow$  Dimension reduction

- Regular multi-resolution:  
Decompose the image into regular blocks



Image



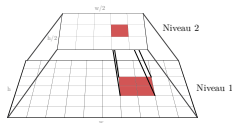
Decomposition into blocks



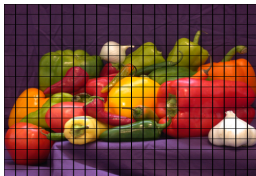
Average colors

Large data  $\rightarrow$  high computational times  $\rightarrow$  Dimension reduction

- Regular multi-resolution:  
Decompose the image into regular blocks
- Superpixels (since [Ren and Malik, 2003]):  
Local grouping of pixels with homogeneous colors



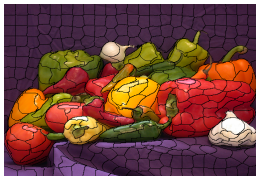
Image



Decomposition into blocks



Average colors



Decomposition into superpixels



Average colors

## Many applications:

- Semantic segmentation:  
[Tighe and Lazebnik, 2010], [Wang and Yushkevich, 2013], [Mostajabi et al., 2015], ...
- Optical flow estimation:  
[Menze and Geiger, 2015], ...
- Style transfer:  
[Liu et al., 2017], ...



## Many superpixel algorithms:

- 2D standard images:  
SLIC [Achanta et al., 2012], LSC [Chen et al., 2017], SNIC Achanta and Süsstrunk [2017], SCALP [Giraud et al., 2018], ...
- Videos:  
[Reso et al., 2013], ...
- Point clouds:  
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- Spherical/Omnidirectional applications: [Zhang et al., 2019], [Yang et al., 2020], ...

Equirectangular image



Projected spherical image



Only one dedicated superpixel algorithm suffering from significant limitations [Zhao et al., 2018]

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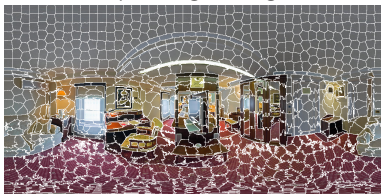


## Many superpixel algorithms:

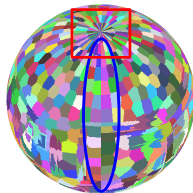
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Standard 2D planar superpixels using [Chen et al., 2017]

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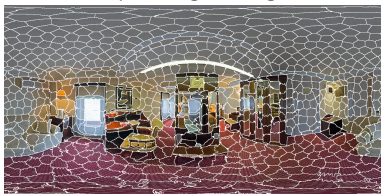


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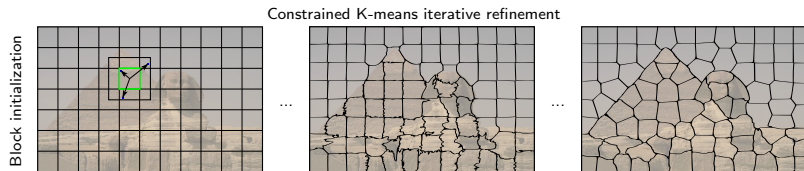


Spherical superpixels using the proposed SphSPS method

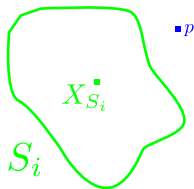
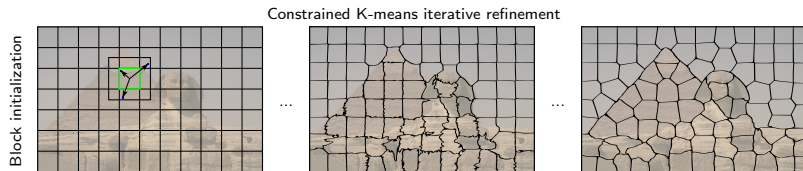
- 1 Introduction
- 2 Spherical SLIC Superpixels (SphSLIC)
- 3 Proposed Spherical Shortest Path-based Superpixels (SphSPS)
- 4 Results



- SLIC: Simple Linear Iterative Clustering [Achanta et al., 2012]



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$C_p = [l_p, a_p, b_p]$  color in the CIELab space

$X_p = [x_p, y_p]$  position

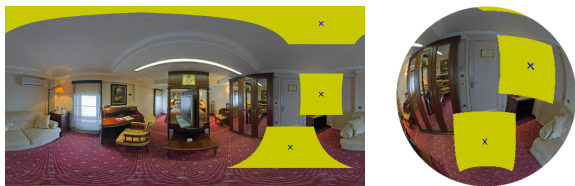
$C_{S_i}, X_{S_i}$  average on pixels  $\in S_i$

Distance between a pixel  $p$  and a superpixel  $S_k$ :

$$D_{\text{SLIC}}(p, S_i) = d_{\text{color}}(C_p, C_{S_i}) + d_{\text{spatial}}(X_p, X_{S_i})$$

Adaptation to spherical geometry: SphSLIC [Zhao et al., 2018]

- Search area: Regular in the acquisition (spherical) space

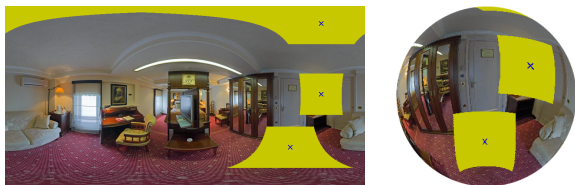


- Spatial distance  $d_{\text{spatial}}(X_p, X_{S_i}) = \|X_p - X_{S_i}\|_2^2$  on spherical coordinates  $X^a$ :

$$X^a = \begin{bmatrix} x^a = \sin\left(\frac{y\pi}{h}\right)\cos\left(\frac{2x\pi}{w}\right) \\ y^a = \sin\left(\frac{y\pi}{h}\right)\sin\left(\frac{2x\pi}{w}\right) \\ z^a = \cos\left(\frac{y\pi}{h}\right) \end{bmatrix} \leftrightarrow X = \begin{bmatrix} x = \lfloor \frac{\arctan2(y^a, x^a)w}{2\pi} \rfloor \\ y = \lfloor \frac{\arccos(z^a)h}{\pi} \rfloor \end{bmatrix}$$

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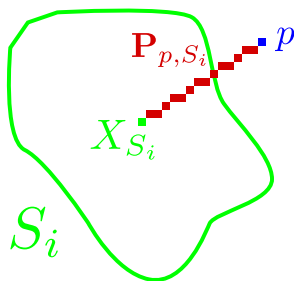
→ Standard SLIC limitations:

- Poor robustness to noise
- Potential irregular shapes
- Low contour adherence performances

## Shortest Path-based Distance:

SCALP (Superpixels with Contour Adherence using Linear Path) [Giraud et al., 2018]

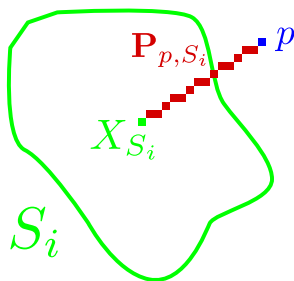
- Color distance of each pixel in linear path  $\mathbf{P}_{p,S_i}$  to the barycenter of the superpixel  
→ Robustness to noise + regular shapes



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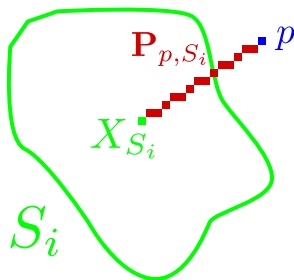
- Color distance of each pixel in linear path  $P_{p,S_i}$  to the barycenter of the superpixel  
→ Robustness to noise + regular shapes
- Maximum of contour map intensity on  $P_{p,S_i}$   
→ Respect of object contours



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Shortest Path-based distance:

$$D_{\text{SPS}}(p, S_i) = (d_{\text{color}}(C_p, C_{S_i}, \mathbf{P}_{p,S_i}) + d_{\text{spatial}}(X_p, X_{S_i})) d_{\text{contour}}(\mathbf{P}_{p,S_i})$$

## Generalized Shortest Path:

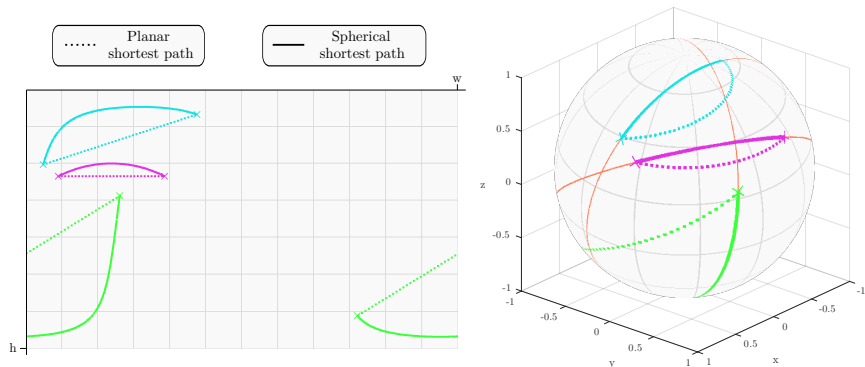
$$\mathbf{P}_{p,S_i} = \mathbf{P}_{p,S_i}^a \xrightarrow{\text{proj}} \{\mathbb{N}^2\}$$

$\mathbf{P}_{p,S_i}$  Path in planar space

$\mathbf{P}_{p,S_i}^a$  Shortest Path in acquisition space

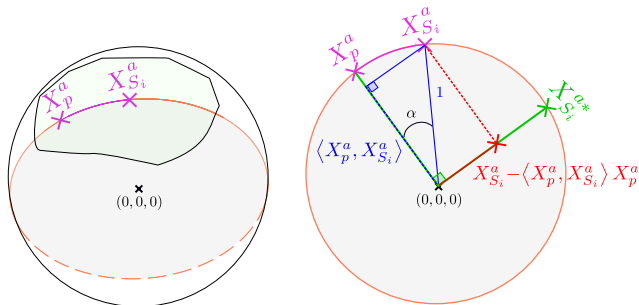
- Spherical acquisition space:

The shortest path  $\mathbf{P}_{p,S_i}^a$  follows the geodesic along the *great circle*





- Fast discrete implementation: Sampling of  $N$  points along the great circle



Coordinate system within the great circle:

$$X_{S_i}^{a*} = \frac{X_{S_i}^a - \langle X_p^a, X_{S_i}^a \rangle X_p^a}{\|X_{S_i}^a - \langle X_p^a, X_{S_i}^a \rangle X_p^a\|_2}$$

→

Radius sampling:

$$P_{p,S_i}^a = \cos(\alpha_N) X_p^a + \sin(\alpha_N) X_{S_i}^{a*}$$

$$\text{with } \alpha_N = \frac{[0, N-1]}{N-1} \alpha \in \mathbb{R}^N$$

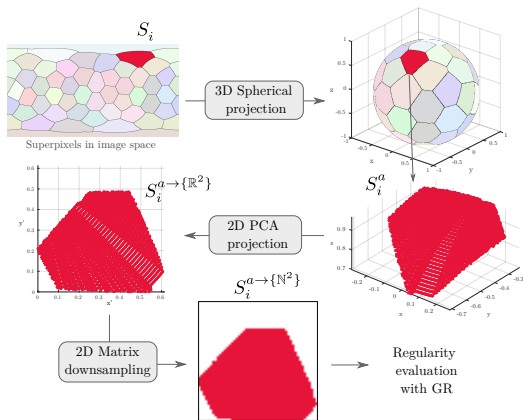
- Recursive optimization using path redundancy:
  - The processing time of SphSPS reduces to 0.7s (for 1024×512 images)

## • Generalized Global Regularity metric (G-GR):

→ Extension of robust Global Regularity using 2D convex hull [Giraud et al., 2017]

For each superpixel shape  $S_i$ :

- 1 Spherical projection on  $\mathbb{R}^3$
- 2 2D PCA projection on  $\mathbb{R}^2$
- 3 Downsampling for dense discretization on  $\mathbb{N}^2$
- 4 Measure of the Global Regularity (GR) with [Giraud et al., 2017]

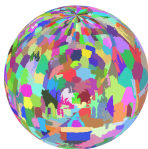


- Comparison for different scales on equirectangular images:

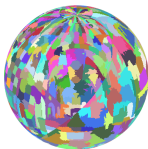
## Planar methods



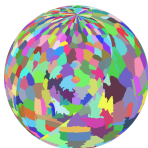
LSC [Chen et al., 2017]



SNIC [Achanta and Süsstrunk, 2017]



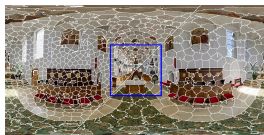
SCALP [Giraud et al., 2018]



## Spherical methods



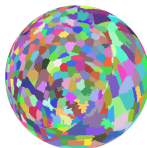
SphSLIC-Euc [Zhao et al., 2018]



SphSLIC-Cos Zhao et al. [2018]



SphSPS



- Comparison for different scales on equirectangular images:



LSC



SNIC



SCALP



SphSLIC-Cos



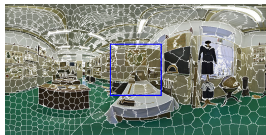
SphSLIC-Euc



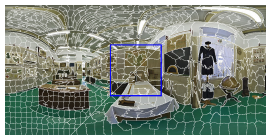
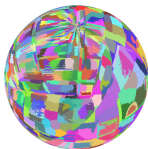
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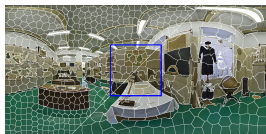
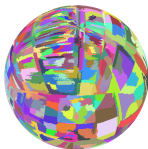
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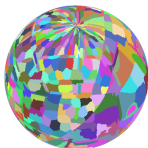
LSC [Chen et al., 2017]



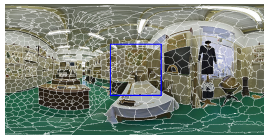
SNIC [Achanta and Süsstrunk, 2017]



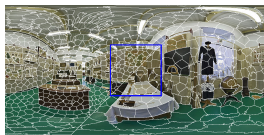
SCALP [Giraud et al., 2018]



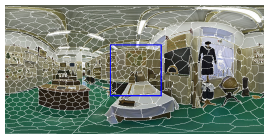
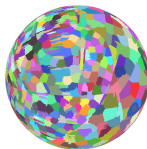
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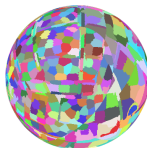
SphSLIC-Euc [Zhao et al., 2018]



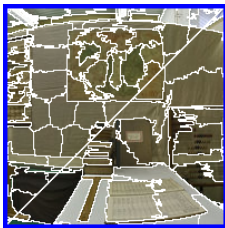
SphSLIC-Cos Zhao et al. [2018]



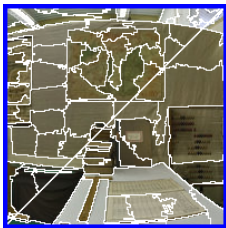
SphSPS



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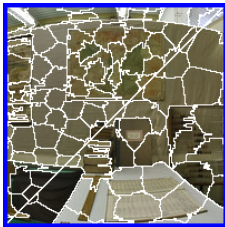
LSC



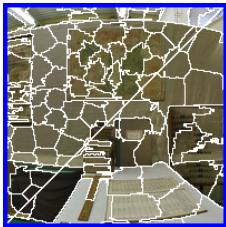
SNIC



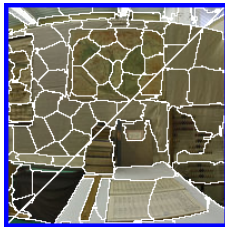
SCALP



SphSLIC-Cos

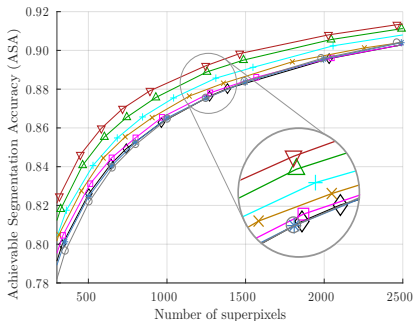
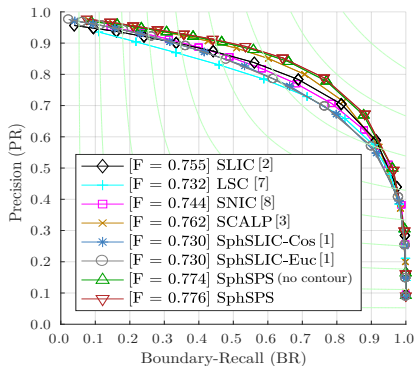


SphSLIC-Euc

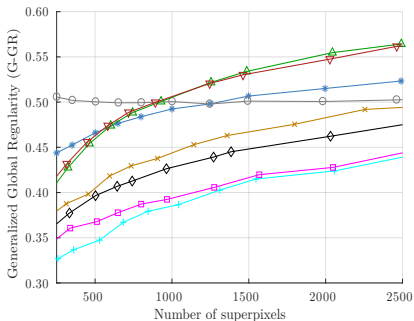
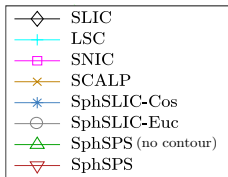


SphSPS

- **Dataset:** Standard *Panorama Segmentation Dataset* (PSD) [Zhao et al., 2018]  
75 equirectangular images of 1024×512 pixels with ground truth segmentation
- **Metrics:**
  - Contour detection: Precision-Recall curves with F-measure (F)
  - Object segmentation: Achievable Segmentation Accuracy (ASA)

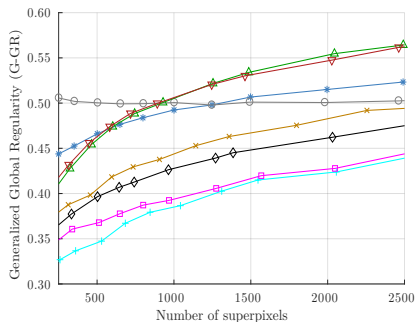
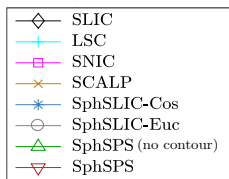


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→ SphSPS has the best accuracy and regularity in the spherical space

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Source code available at:

<https://github.com/rgiraud/sphsps>

Check other superpixel works at:

<http://rgiraud.vvv.enseirb-matmeca.fr>



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