

Revisiting the Training of Very Deep Neural Networks without Skip Connections

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**Presentation by
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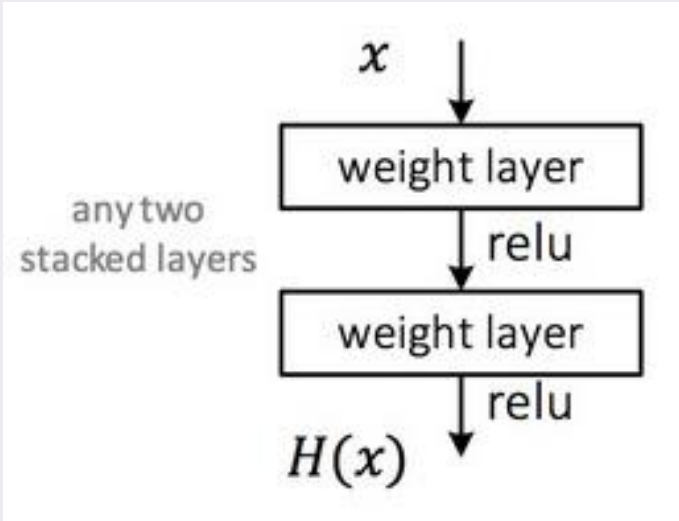
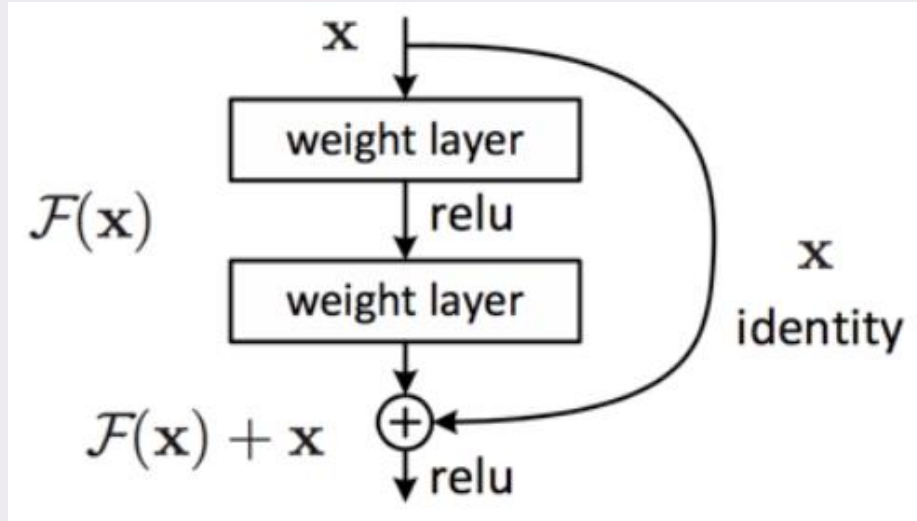
Outline

1. Introduction
2. Investigation
3. Alleviating the training problems of very deep PlainNets
4. Experiments
5. Conclusion

Introduction: training Very Deep Neural Networks

Very deep models:

- ❑ These are deep neural networks (DNNs) with over 15 layers

	<u>PlainNets (i.e. no skip connections)</u>	<u>Deep Neural Networks with Skip Connections</u>
Features	<ul style="list-style-type: none">• Few layers• Simple architectures• Difficult optimization• Model operation is explainable [1]	<ul style="list-style-type: none">• Several layers• Complicated architectures• Easy optimization• Model operation is unclear [1, 2, 3, 4]
Architecture	<ul style="list-style-type: none">• No skip connections  <p>any two stacked layers</p>	<ul style="list-style-type: none">• With skip connections 

Introduction: training very deep PlainNets is difficult

Problem statement:

- ❑ Training very deep PlainNets become difficult with depth increase

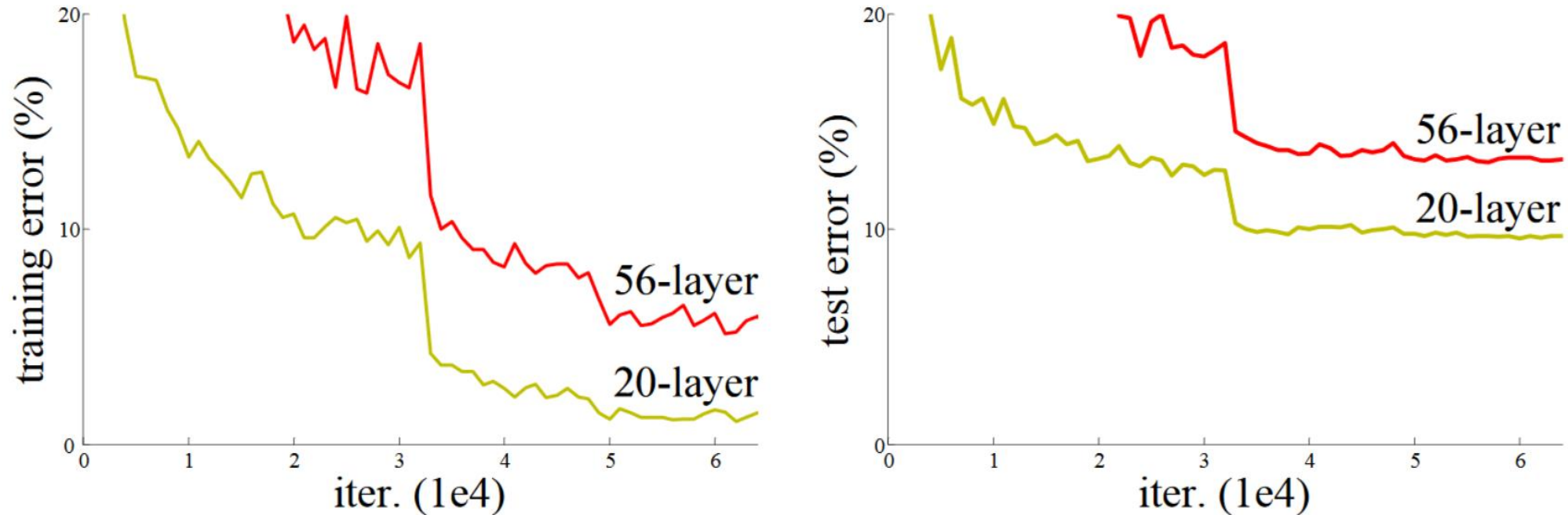
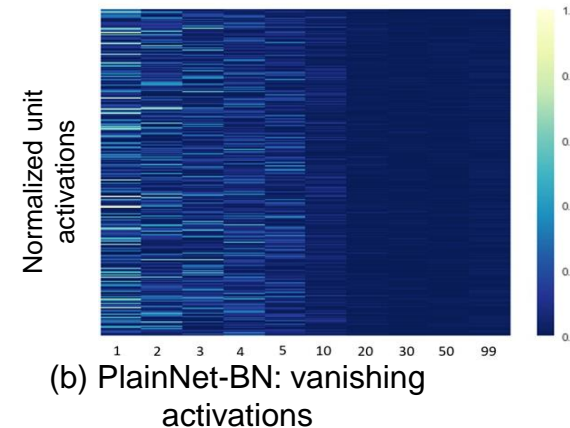
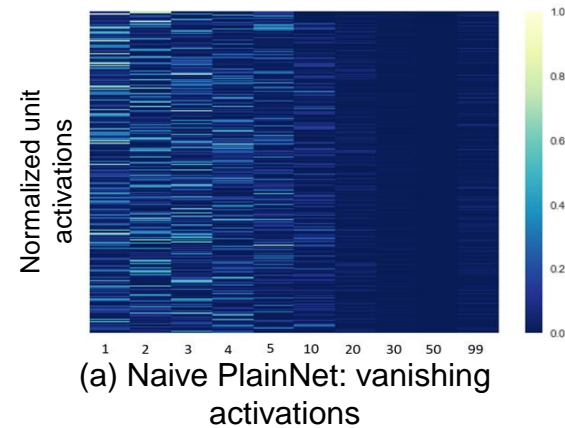


Fig. 2. Error rate increase on the very deep PlainNets trained on CIFAR-10 dataset [5]

Investigation: vanishing/exploding units' outputs

- Units' outputs decrease globally with depth

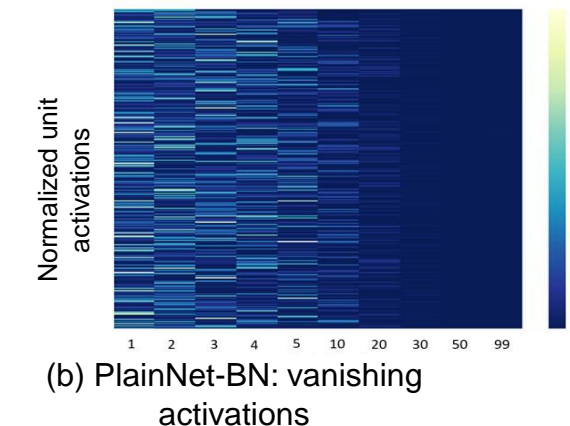
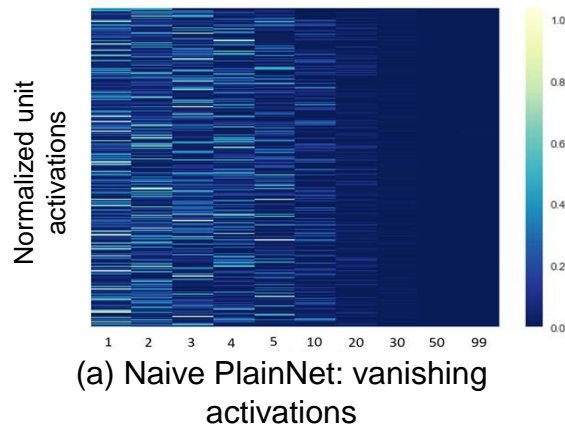
Normalized mean layer activations
for a 100 layer PlainNet over COIL-20
dataset



Keys:

- BN → batch normalization [6]
- Naïve PlainNet → no BN
- PlainNet-BN → with BN

Normalized mean layer activations
for a 100 layer PlainNet over USPS
dataset

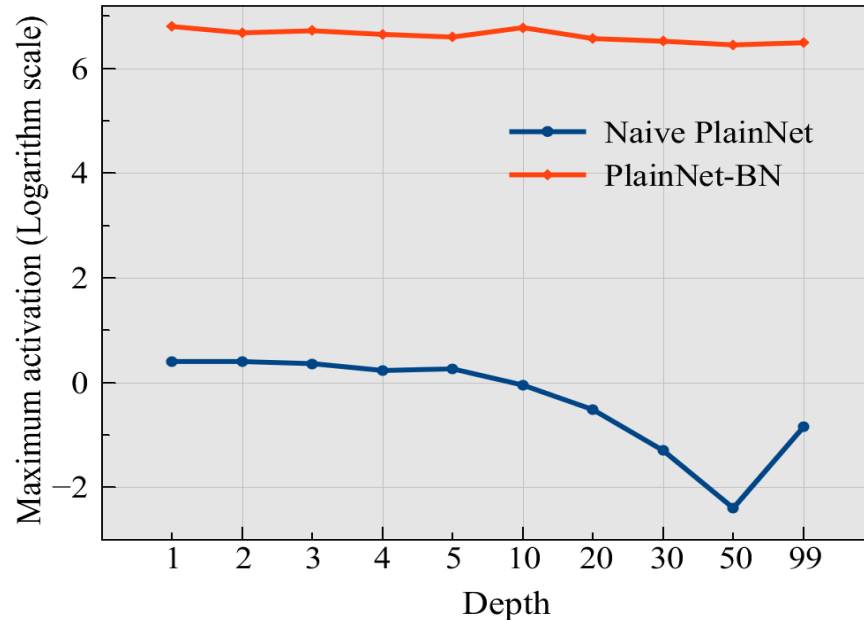


Highlights:

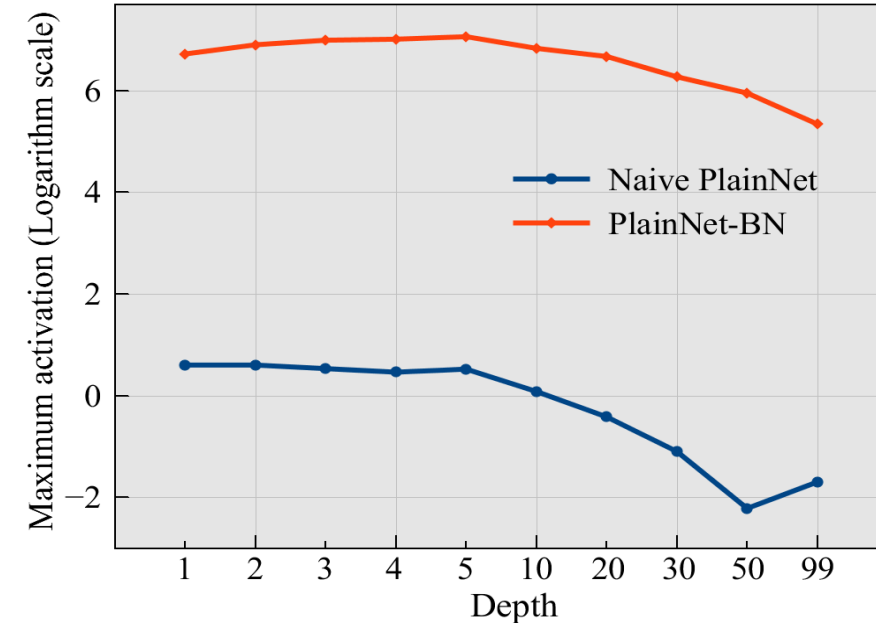
1. Units' outputs decay → info loss

Investigation: vanishing/exploding units' outputs

- Units' in PlainNet-BN have extremely high outputs



COIL-20 dataset

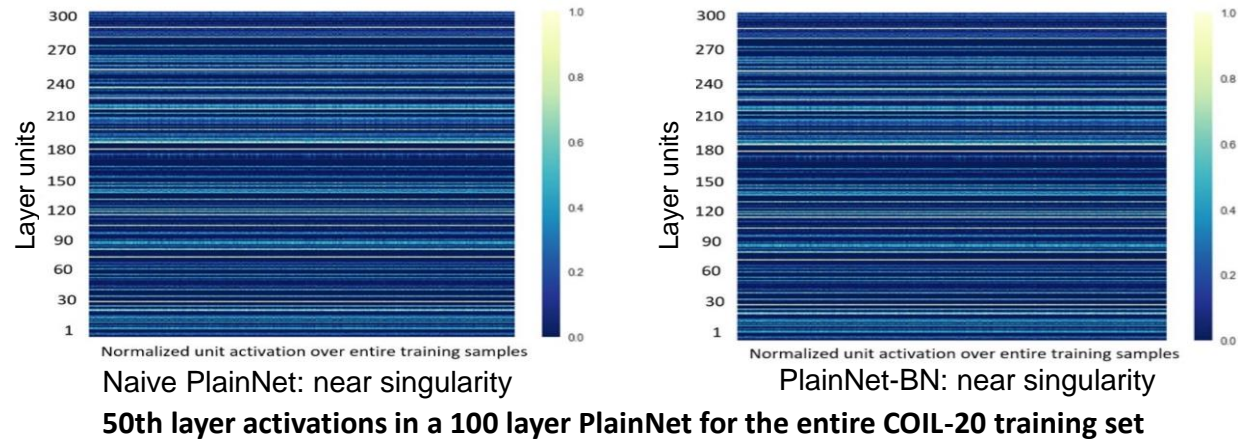


USPS dataset

Highlight:

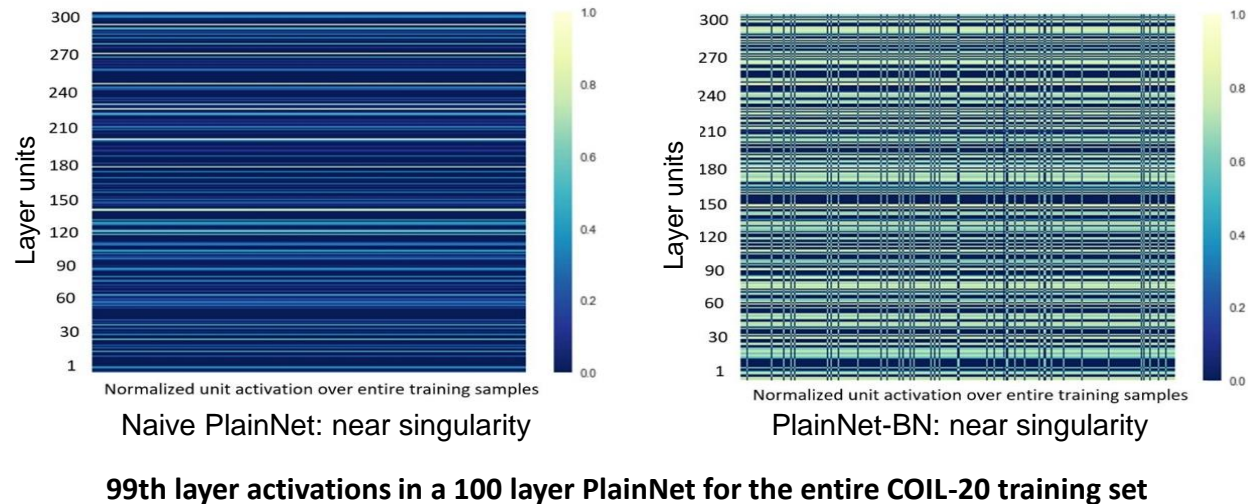
Extremely high or small outputs → bad optimization

- Units respond in similar fashion to different training samples



Highlights:

1. Units' response \rightarrow near-singularity
2. Near-singularity \rightarrow high condition number
3. High condition number \rightarrow bad optimization



□ Components of the proposed approach

- **Leaky Rectified Linear Unit (LReLU) → vanishing/exploding units' outputs**

$$H(x)^l = 1(Z^l \leq 0)(\beta Z^l) + 1(Z^l > 0)(Z^l), \quad (1)$$

where Z^l and β are the pre-activation and leaky scaling factor, respectively.

- **Max-norm constraint → exploding unit's output**

$$\|\vec{w}_j\| \leq c, \quad (2)$$

where c is the specified max-norm.

- **Weight initialization from uniform distribution → weight diversity**

$$U[\sqrt{6/n_{in}^l}, -\sqrt{6/n_{in}^l}], \quad (3)$$

where n_{in}^l is the number of units feeding into layer l .

Experimental results: proposed solution (PlainNet)

□ Table 1: Ablation studies – 100 layer model results using USPS dataset

Model component	Train error	Test error
Batch normalization (BN)	84.56%	83.21%
LReLU	92.37%	92.03%
Max-norm	86.22%	86.85%
BN + LReLU	78.38%	79.52%
BN + max-norm	82.90%	81.86%
LReLU + max-norm	83.62%	82.11%
Proposed: BN + LReLU + max-norm	0.11%	5.48%

Highlight:

Proposal → the three components
give the best results

□ Table 2: Model results using CIFAR-10 dataset

Model	Skip conn.	Layers	Parameters	Test error
Highway network [2]	Yes	19	2.30M	7.54%
ResNet [3]	Yes	56	0.85M	6.97%
ResNet [3]	Yes	110	1.7M	6.43%
All CNN [30]	No	8	1.30M	7.25%
NiN [31]	No	10	1.30M	8.81%
Delta init. [15]	No	32	17.80M	18.00%
PlainNet-BN [3]	No	56	0.85M	15.00%
Proposed PlainNet	No	50	0.72M	6.65%

Highlight:

Proposal → successful training

Paper highlights:

- ❑ Revisited the problem of training very deep networks without skip connections
- ❑ Proposed an approach to tackle identified problems
- ❑ The proposed DNN is seen to outperform similar models without skip connections
- ❑ The proposed DNN without skip connections achieve competitive results in comparison to DNNs with skip connections.

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3. Balduzzi, D., Frean, M., Leary, L., Lewis, J. P., Ma, K. W. D., & McWilliams, B. (2017, August). The shattered gradients problem: if resnets are the answer, then what is the question?. In Proceedings of the 34th International Conference on Machine Learning-Volume 70 (pp. 342-350).
4. Greff, K., Srivastava, R. K., & Schmidhuber, J. (2017). Highway and residual networks learn unrolled iterative estimation. International Conference on Learning Representations.
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Thank you !