



Uncertainty-sensitive Activity Recognition: a Reliability Benchmark and the CARING Models

International Conference on Pattern Recognition (ICPR)

Computer Vision for Human-Computer Interaction Lab (cv:hci) Institute for Anthropomatics and Robotics (IAR)

Alina Roitberg



Monica Haurilet



Manuel Martinez



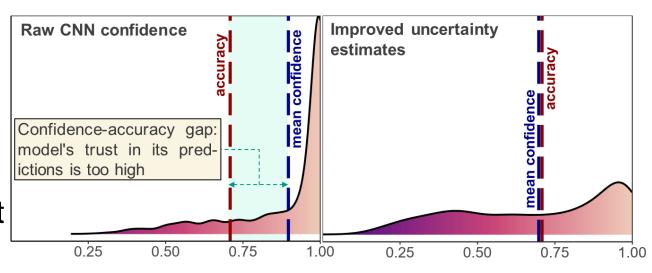
Rainer Stiefelhagen



Highlights



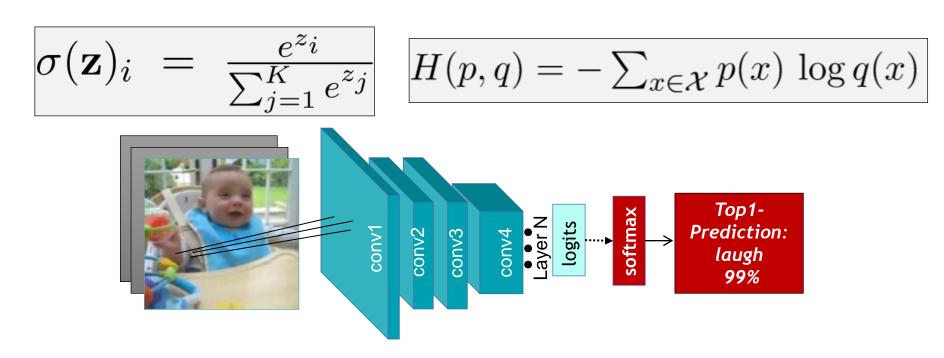
- Goal: Action Recognition (AR) with reliable confidence estimates
- First study of reliability of confidence values in modern AR architectures
- Improving the reliability of model confidence in action recognition:
- Enhancing the AR models with temperature scaling (Guo et al.)
- Calibrated Action Recognition with Input Guidance (CARING): a new learning technique to scale the logits depending on the video input



A note on Softmax



- Normalizes the output of the last fully-connected layer
- The outputs sum up to one (often inaccurately called "probabilities")
- Input to Cross-Entropy loss, usually to maximize the Top-1 accuracy
- → Excellent Top-1 action recognition results, but does it reflect the true confidence?

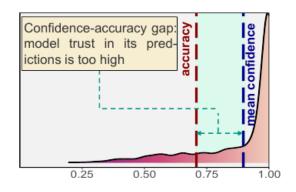


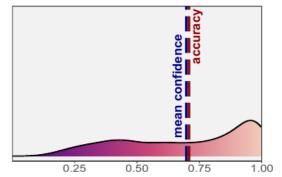
Expected Calibration Error

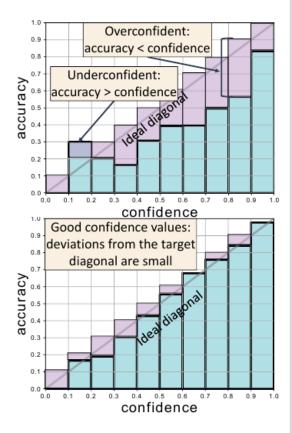


- We integrate reliability of model confidence in the activity recognition evaluation
- We present a learning-based approach for improving it
- What is a good confidence value?
 - Metrics: Expected Calibration Error (ECE)
 - Visualized with reliability diagrams

$$ECE = \sum_{i=1}^{K} \frac{N_{bin_i}}{N_{total}} |acc(bin_i) - conf(bin_i)|$$







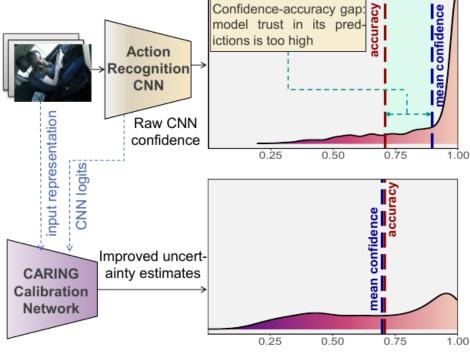
CARING: Calibrated Action Recognition with Input Guidance



We present a learning-based approach for reliable confidence estimates

 Calibrated Action Recognition with Input Guidance (CARING)

Coarse idea: additional network learning to scale the logits depending on the input



 Compared to native action recognition architectures and temperature scaling, where a single scaling factor is learned (Guo et al., 2017)

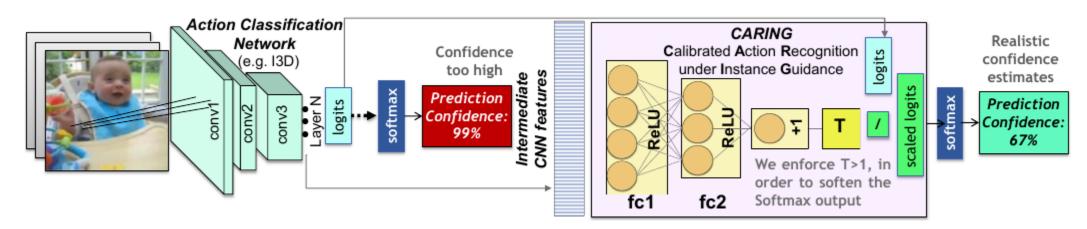
Learning Proper Confidence Estimates



- The CARING network produces different temperature values T(z) depending on the input z
- The logits are scaled by T(z), the final confidence becomes:

$$conf(a_{pred}) = \max_{a \in \mathcal{A}} \frac{exp(\frac{y_a}{\mathcal{T}(\vec{z})})}{\sum_{\hat{a} \in \mathcal{A}} exp(\frac{y_{\hat{a}}}{\mathcal{T}(\vec{z})})}$$

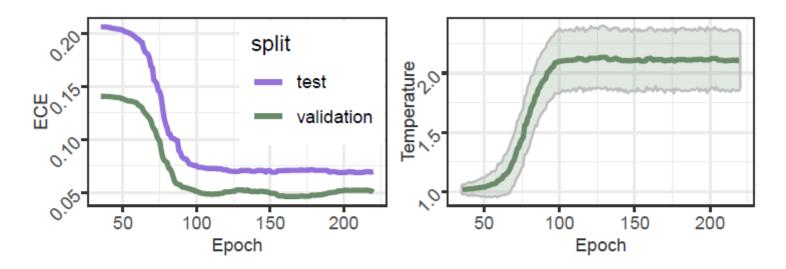
Trained on a held-out validation set



Learning Proper Confidence Estimates



CARING model evolution during training

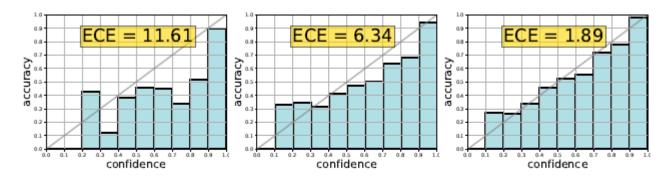


(a) Expected Calibration Error im-(b) Average temperature and its provement during the training prostandard deviation estimated by cedure for validation and test data.

Confidence Estimates Study



- Original models poor confidence estimates
- Clearly improved by Temperature Scaling
- Our CARING model leads to the best results
- Still: a lot of room for improvement for underrepresented classes!



(a) I3D (original), all action classes

(b) I3D + temp. scal-(c) CARING-I3D, ing, all action classes all action classes

Model	ECE		NLL		
	validation	test	validation	test	
Drive&Act - Common Classes					
P3D [61] §	16.9	19.39	1.63	1.85	
I3D [6] S	10.22	13.38	0.90	1.27	
P3D + Temperature Scaling [20]	5.65	5.7	1.28	1.48	
I3D + Temperature Scaling [20]	5.31	6.99	0.57	0.83	
CARING - P3D (ours) ①	4.81	4.27	1.19	1.42	
CARING - I3D (ours) (0	2.57	5.26	0.50	0.78	
Drive&Act - Rare Classes					
P3D [61] S	31.49	37.25	3.43	4.68	
I3D [6] S	31.48	43.32	3.41	4.54	
P3D + Temperature Scaling [20] (1)	17.83	21.09	2.26	2.99	
I3D + Temperature Scaling [20] (1)	24.97	32.38	1.96	2.62	
CARING - P3D (ours) (1)	13.73	19.92	2.12	2.93	
CARING - I3D (ours) (0	18.34	23.6	1.55	2.17	
Drive&Act - All Classes					
P3D [61] S	17.89	21.09	1.77	2.12	
I3D [6] S	11.72	15.97	1.10	1.56	
P3D + Temperature Scaling [20] ①	5.89	6.41	1.35	1.63	
I3D + Temperature Scaling [20] (1)	6.59	8.55	0.68	0.99	
CARING - P3D (ours) (1)	4.58	5.26	1.26	1.57	
CARING - I3D (ours) ①	3.03	6.02	0.58	0.9	
HMDB-51					
I3D [6] (S)	10.29	20.11	0.98	1.97	
I3D + Temperature Scaling [20] (1)	4.00	7.75	0.81	1.57	
CARING - I3D (ours) ①	3.38	5.98	0.81	1.54	
Standard activity recognition mode	els 🛈 Ur	U Uncertainty-aware models			



Thank you for your attention!

Check out our paper©

"Uncertainty-sensitive Activity Recognition: a Reliability Benchmark and the CARING Models"

Alina Roitberg, Monica Haurilet, Manuel Martinez, Rainer Stiefelhagen