VTT: Long-term Visual Tracking with Transformers

Presentation, ICPR 2020

Tianling Bian Shanghai Jiao Tong University, China **Yang Hua** Queen's University Belfast, UK

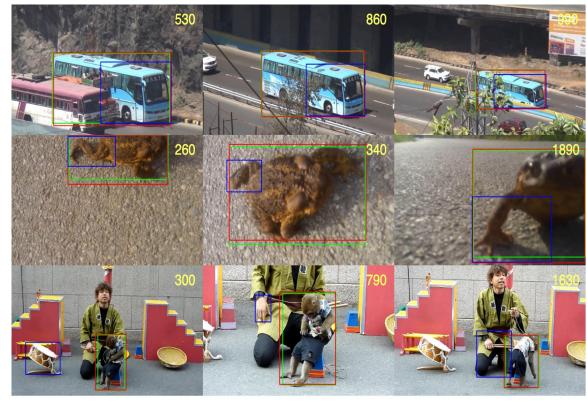
Tao Song Shanghai Jiao Tong University, China **Zhengui Xue** Shanghai Jiao Tong University, China

Ruhui Ma Shanghai Jiao Tong University, China Neil Robertson Queen's University Belfast, UK

Haibing Guan Shanghai Jiao Tong University, China

Goal

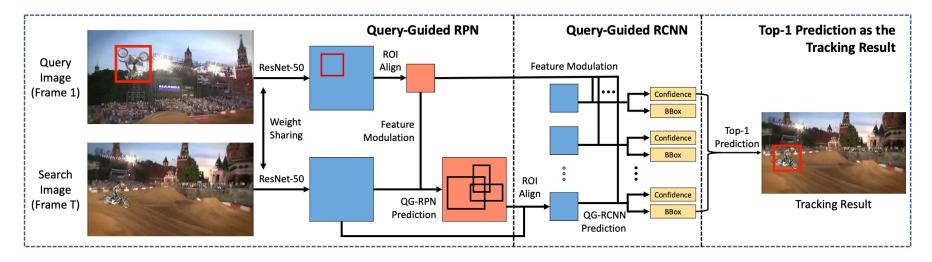
- Long-term visual tracking
- Difficulties
 - Occlusion
 - Scale and ratio variation
 - Distractors



Ground Truth

Related Work

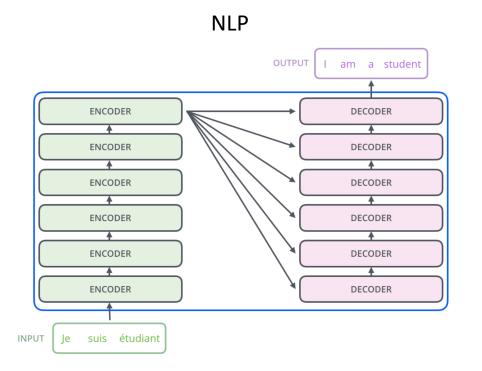
- GlobalTrack*
 - Unable to handle Occlusion, scale and ratio variation
 - Inferior performance against instance level distractors



* GlobalTrack: A Simple and Strong Baseline for Long-Term Tracking. Huang, Zhao, and Huang. AAAI 2020

Our Method

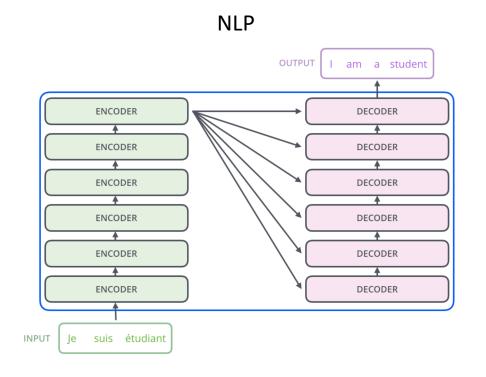
• Transformers* were first proposed for machine translation

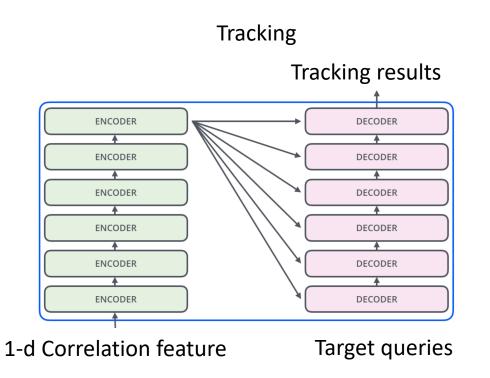


* Attention is all you need. Ashish, et al. NeurIPS 2017

Our Method

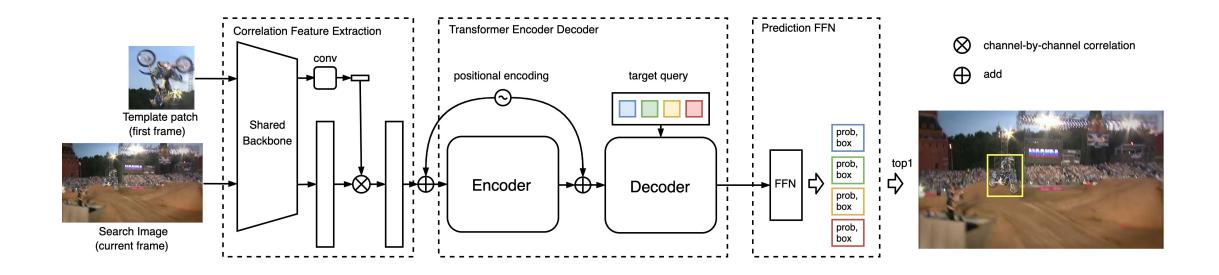
• We adapt this architecture for tracking





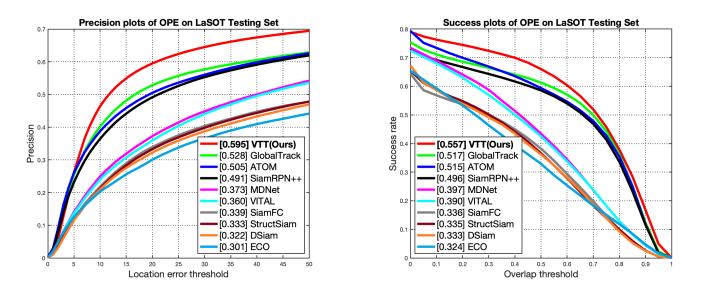
Our Method

• End to end trainable simple architecture



Experiment: Results

 Significant improvement compared to GlobalTrack on LaSOT* as well as other long-term tracking datasets.



* Lasot: A high-quality benchmark for large-scale single object tracking. Heng, et al. CVPR 2019

Experiment: Encoder Attention

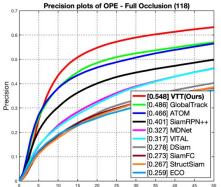
- Lower level attention focus on visuals
- Higher level attention focus on semantics
- Attend to disconnected regions



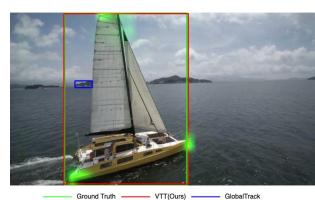
Experiment: Decoder Attention

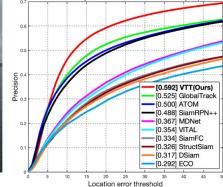


Ground Truth _____ VTT(Ours) _____ GlobalTrack

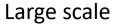


Location error threshold

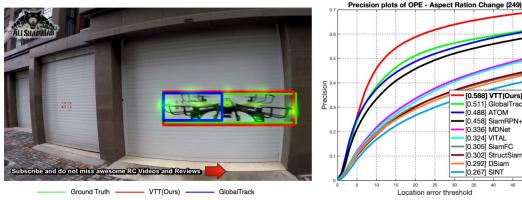


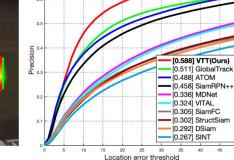


Precision plots of OPE - Scale Variation (273)



Occlusion

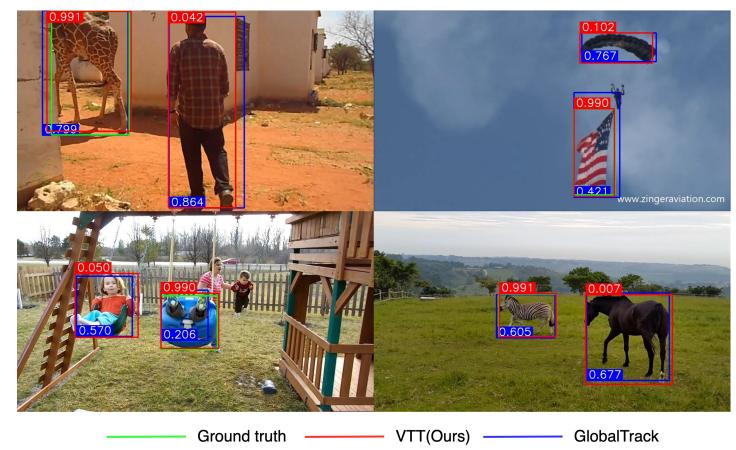




Extreme aspect ratio

Experiment: Distractors

• Compared to GlobalTrack, our method is significantly better



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