

# Directionally Paired Principal Component Analysis for Bivariate Estimation Problems

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### Contributions

- Propose Directionally Paired Principal Component Analysis (DP-PCA): optimal linear model for estimating coupled yet partially observable variables
  - Directly minimizes prediction errors rather than maximizing cov/corr
  - Lower prediction errors compared to existing linear cross-decomposition methods (PLS/CCA [1, 2])

[1] J. A. Wegelin et al., "A survey of partial least squares (pls) methods, with emphasis on the two-block case," University of Washington, Tech. Rep, 2000.
[2] H.Hotelling, "Relations between two sets of variates." Biometrika, vol. 28, no. 3/4, pp. 321–377, 1936.

 Propose Directionally Pained Principal Component Analysis (DP-AC4): optimal linear model for extinnaling coupled jet partially observable variables
 Directy initiatis predictor errors rather than maximizing conform Linear predictor errors compared to acting linear cross-decompasion methods (PS/OCA)(1, 2)

#### Dimension reduction and PCA

- Complexity in raw data
   Dimension of useful feature < dimension of data</li>
- PCA: single-variable set
  - Maximize variance

$$\mathbf{w}_{(1)} = \arg \max \left\{ \frac{\mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w}}{\mathbf{w}^T \mathbf{w}} \right\}$$

• Minimize reconstruction error

$$\varepsilon(A, U) = \frac{1}{N} \sum_{n=1}^{N} ||\mathbf{x}_n - U\mathbf{a}_n||^2$$



PCA of a multivariate Gaussian distribution. (source: Wikipedia)



# Objective: coupled, partially observable data

• Training



Testing

$$\begin{bmatrix} \mathbf{x} \end{bmatrix}_{M_1 \times N}^{\text{test}} \xrightarrow[\text{reduction}]{}^{\text{test}} \begin{bmatrix} \mathbf{a} \end{bmatrix}_{L \times N}^{\text{test}} \xrightarrow[\text{transform}]{}^{\text{inverse}} \begin{bmatrix} [\mathbf{\hat{x}}]_{M_1 \times N}^{\text{test}} \\ [\mathbf{\hat{y}}]_{M_2 \times N}^{\text{test}} \end{bmatrix}$$



#### Proposed DP-PCA

Least squares formulation

$$\varepsilon_Y(U, V) = \frac{1}{N} \sum_{n=1}^N ||\mathbf{y}_n - V U^T \mathbf{x}_n||^2$$

• Optimality conditions  $\begin{cases}
XX^TU = XY^TV(V^TV)^{-1} \\
V = YX^TU(U^TXX^TU)^{-1}
\end{cases}$ 

(Derivation in Section II.)

• Solution steps

- 1. Solve eigenvalue problem on the  $N \times N$  matrix  $YY^T$ :  $Y^TYZ = ZD$
- 2. Solve  $X^T U = Z$  for U. (Z with size  $N \times L$  contains L eigenvectors.)
- 3. Plug in optimality condition for V

#### (DC-PCA: obtain U via PCA on X. Concurrent work [3].)

[3] N. Dahiya, Y. Fan, S. Bignardi, R. Sandhu, and A. Yezzi, "Dependently Coupled Principal Component Analysis for Bivariate Inversion Problems," 2020 25th International Conference on Pattern Recognition. IEEE, 2020.



#### Comparison with related approaches



Partial Least Square Regression (PLSR)

- Paired loadings P, Q and weights W, C by maximizing covariance of standardized data
- Regression in subspaces



Canonical Regression (CR)

- Paired orthonormal bases U, V by max variance of standardized data
- Regression and maximizing covariance terms in subspaces



**Proposed DP-PCA** 

- Orthonormal basis *U* for *X* by maximizing variance
- Paired basis V for Y by minimizing reconstruction error under shared coefficient  $\mathbf{a}_n^*$

#### Comparison on storage requirement

Method	Results to be stored after training
Joint PCA	$\overline{X}$ , $\overline{Y}$ : mean values of training data (with size $M_1$ and $M_2$ ); $U, V$ : bases for X and Y (with size $M_1 \times L$ and $M_2 \times L$ ).
PLSR	$\overline{X}, \overline{Y}$ : mean values of training data (with size $M_1$ and $M_2$ ); $\sigma_X, \sigma_Y$ : standard deviation of training data (with size $M_1$ and $M_2$ ); $\mathbf{P}, \mathbf{X}_{rotations}$ : loadings and rotations for $\mathbf{X}$ (two matrices both with size $M_1 \times L$ ); Either (1) $\boldsymbol{\beta}$ : regression coefficient for predicting $\mathbf{Y}$ from $\mathbf{X}$ (with size $M_2 \times M_1$ ) or (2) $\mathbf{R}$ : regression matrix between $\mathbf{A}$ and $\mathbf{B}$ (with size $L \times L$ ), $\mathbf{Q}$ : loadings for $\mathbf{Y}$ (with size $M_2 \times L$ ).
CR	$\overline{X}$ , $\overline{Y}$ : mean values of training data (with size $M_1$ and $M_2$ ); $\sigma_X$ , $\sigma_Y$ : standard deviation of training data (with size $M_1$ and $M_2$ ); <b>U</b> , <b>V</b> : loadings for $X$ and $Y$ (with size $M_1 \times L$ and $M_2 \times L$ ) $\overline{A}$ , $\overline{B}$ : mean values in the subspace (with size $L$ ) $\sigma_A$ , $\sigma_B$ : standard deviation in the subspace (with size $L$ ) $\beta$ : correlation coefficient between <b>U</b> and <b>V</b> (with size $L \times L$ )
DP-PCA	Same as those in Joint PCA

### Evaluation via reconstruction and prediction





## Experiment result: synthetic data

• Multivariate Gaussian distribution w/ random mean and covariance



Independent: lower bound, best possible Joint PCA: worst as  $Y_{test}$  unobservable CR: sub-optimal for both  $X_{test}$  and  $Y_{test}$ PLSR: sacrificing  $X_{test}$  for better  $Y_{test}$ DC-PCA: best  $X_{test}$  and total, descent  $Y_{test}$ Best combination: PCA for  $X_{test}$  and

Figure 6.5: Evaluation on dimension reduction via data reconstruction and prediction of coupled synthetic data.  $N = 10^4$ ,  $M_1 = M_2 = 128$ , L = 1 to 32. Horizontal axis: dimension L of the target subspace (i.e., budget); vertical axis: reconstruction/prediction error.

Best combination: PCA for  $X_{test}$ , and optimal Y mode of DP-PCA for  $Y_{test}$ 



### Execution time

• Experience with publicly available implementations



PLSR: <u>https://scikit-learn.org/stable/modules/generated/sklearn.cross\_decomposition.PLSRegression.html</u> CR (R): <u>https://rdrr.io/github/jmhewitt/telefit/man/cca.predict.html</u> CR (Python): <u>https://gist.github.com/thelittlekid/89630241f5b90a838a7b583a5836d350</u>



#### Experiment result: multi-target regression



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### Experiment result: single-channel images



Sequential split: according to the sequence of indices (i.e., top vs bottom) Random split: randomly yet consistently across images

DP-PCA: for random split, achieve best results on all three under the budget of a single-pair bases.



#### Conclusions

- Best (combined) estimation of coupled yet partially observable data:
  - Standard PCA for the observable part X
  - Optimal Y mode of DP-PCA for the unobservable part Y
  - More storage requirement (two pairs of bases) and longer computation time
- DC-PCA: best single approach for overall estimation
  - Suitable when the unobservable are no more important than the observable
  - Lowest storage requirement and fast speed